## OMRON



» Flexible !

» Fast!

» Small!

realizing

# The Fast, Small, and Flexible CJ1 the World of Machine Control!

## Fast!

Versatile Machine Control with the Highest Performance Standards in the Industry.



### **Upgraded Basic Functions**

(CJ1H-CPU6□H-R Performance

instructions

Scan time 30 Ksteps in 870 µs

PCMIX values 17

Basic instructions LD 16 ns/OUT 16 ns Floating-point decimal Add/subtract: 0.24  $\mu$ s

Multiply: 0.24 µs

Interrupt response time 40 µs

● Conditions: 30 Ksteps, basic-to-special instruction ratio = 7:3, 128 inputs, 128 outputs

## Small!

Super-compact design that meets the highest standards in its class. Even a narrow space in a machine serves as a control panel.



Height: 90 mm, Depth: 65 mm

Backplane-free structure for a flexible Rack width.

**Smaller Units.** 

# Programmable Controller S/SI/IAC

## Expands

## Flexible!

Suitable for essentially any application, from small device and temperature control, to large-scale control over networks.



### **Wide Range of CPU Units**

Program capacity: 5 to 250 Ksteps
I/O points: 160 to 2,560 points
Data memory capacity: 32 to 448 Kwords

### **Application-specific CPU Units**

CPU Units are available for a variety of applications, such as CPU Units with built-in I/O, CPU Units with Ethernet function, or CPU Units for loop control.

### **Full Complement of I/O Units**

From Basic I/O Units, Analog Units, and Position Control Units to Ethernet Units, any of the Units can be used with any of the CPU Units.

## CONTENTS

Concept 2

System Design Guide	17
System Configuration	18
Dimensions	22
■ General Specifications	25
<b>■</b> Common Specifications for CPU Units	28
<b>■CJ1M-CPU2</b> (CJ1M CPU with Built-in I/O)	
Specifications	32
<b>■</b> CJ1M-CPU1 :-ETN (CJ1M CPU with	
Ethernet function) Specifications	
■CJ1G-CPU□□P  (Loop-control CPU Units)	
Specifications	35
Checking Current Consumption and	
Power Consumption	36
Ordering Information	37
Basic Configuration Units	38
Programming Devices	42
Optional Products and Maintenance	
Products	45
■ DIN Track Accessories	45
Basic I/O Units	46
Special I/O Units and CPU Bus Units	50

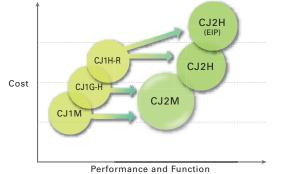


New CJ2 series introduction

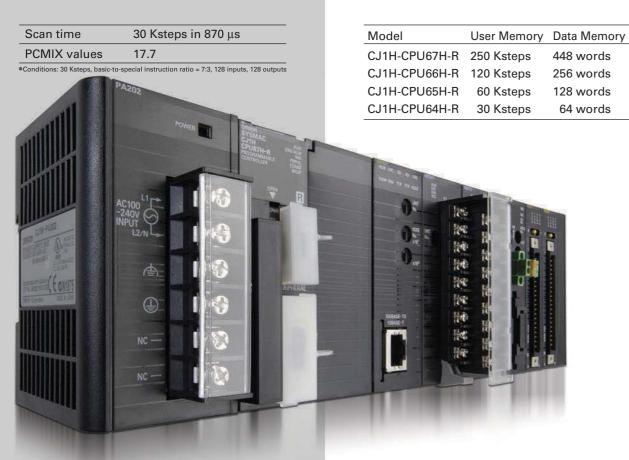
With the base of CJ1 series, CJ2
series with advanced functions has been released.

The CJ2 series will easily innovate your systems widely ranging from compact machinery to high-speed and highly precise systems.

Refer to the catalog (Cat No. P059) for details.



## Expanding the Possibilities of Machine Control: Fast New Flagship "R" CPU Units for the CJ1 Series.



All Processes Speeded Up for Enhanced Application Performance.

### Fast! System Overhead

Common processing 130 μs
Interrupt response 40 μs

### **Fast!** Basic Instructions

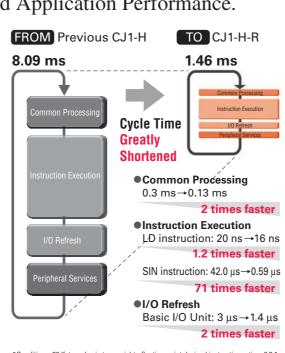
LD instruction execution time 16 ns OUT instruction execution time 16 ns

### **Fast!** Floating-point Arithmetic

SIN calculation 0.59 µs
Floating-point decimal 0.24 µs
addition and subtraction

### Fast! I/O Refresh

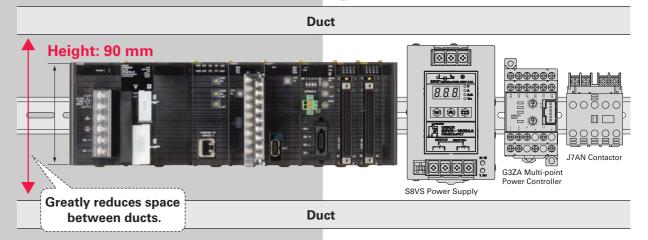
Basic I/O Unit, 16 points 1.4 μs Analog Input Unit, 8 points 50 μs



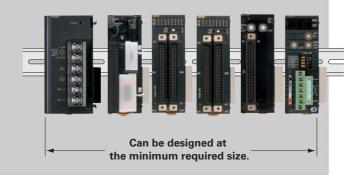
Super-compact design that meets the highest standards in its class. Even a narrow space in a machine serves as a control panel.

Compact Size Saves Space when Incorporated into Machines. Contributes to Size Reduction in Devices and to Space Savings in Control Panels.

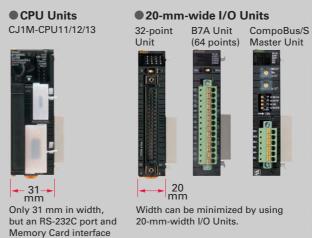
Super Compact: Only 90 mm High and 65 mm Deep. Can Be Mounted in a Control Panel with Other Small Components.

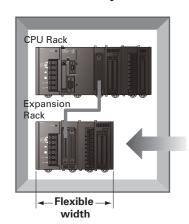


Backplane-free Structure Enables Flexible-width Design. Using I/O Units on Expansion Racks Further Improves Space Efficiency in Control Panels.



### A Variety of Compact Units

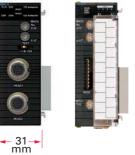




Using I/O Units on Expansion Racks enables installation in narrow spaces.

### ●31-mm-width I/O Units

ID Sensor Unit Temperature Control Unit (2 Channels) (4 Loops)



A variety of Units are available for high-density mounting.
Using Units for external devices enables further size reductions.

Conditions: 30 Ksteps, basic-to-special-to-floating-point decimal instruction ratio = 6:3:1, 128 inputs. 128 outputs. 2 Analog Input Units. 2 Position Control Units (4-axis Units)

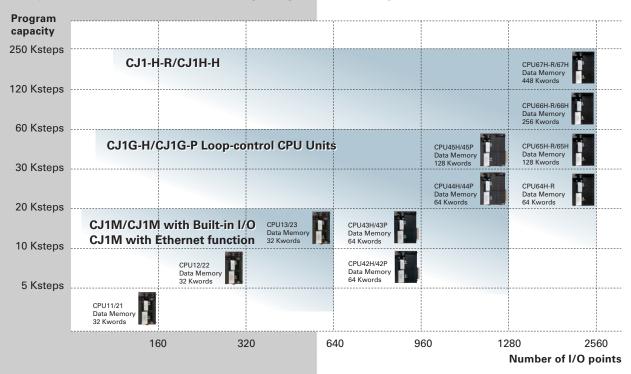


Suitable for any application, from small device and te mperature control, to large-scale control over networks.

## A Wide Variety of CPU Units and Other Units to Handle Virtually Any Type of Machine Control.

### A Complete Lineup of CPU Units, from Low-end to High-end

Despite the wide variety of models, memory allocations, instructions, and I/O Units are all compatible. This makes it easy to design migration from large-scale systems to small devices.



### A Wide Selection of CPU Units to Match the Application

Select the optimum CPU Unit according to your system requirements.

	General-purpose CPU Units					Application-specific CPU Units		
	High-speed Models	Advanced Models	Standard Models	Compact Models	with Built-in I/O	with Ethernet function	Loop-control CPU Units	
	For Applications Requiring Speed	For Large-scale Applications Requiring Large Memory Capacity	For Applications Requiring Large Memory Capacity, such as Data Management	For Small-scale Applications such as Automated Machines and Inspection Devices	For Applications Requiring Versatile, High-precision Position Control	For Applications Requiring Ethernet network	For Applications Requiring Sequence Control and Analog Control	
CPU Unit	CJ1H-	CJ1H-	CJ1G-	CJ1M-	CJ1M-	CJ1M-	CJ1G-	
	CPU6□H-R	CPU6□H	CPU4□H	CPU1□	CPU2	CPU1□-ETN	CPU4□P(-GTC)	
						i di		
Basic instructions	LD 16ns/OUT 16ns	LD 20ns/OUT 20ns	LD 40ns/OUT 40ns	LD 100ns/OUT 350ns	LD 100ns/OUT 350ns	LD 100ns/OUT 350ns	LD 40ns/OUT 40ns	
Program capacity	250 to 30 Ksteps	250 to 60 Ksteps	60 to 10 Ksteps	20 to 5 Ksteps	20 to 5 Ksteps	20 to 5 Ksteps	60 to 10 Ksteps	
Data memory capacity	448 to 64 Kwords	448 to 128 Kwords	128 to 64 Kwords	32 Kwords	32 Kwords	32 Kwords	128 to 64 Kwords	
Number of I/O points	2,560	2,560	1,280 to 960	640 to 160	640 to 160	640 to 160	1,280 to 960	
Width	62 mm	62 mm	62 mm	31 mm	49 mm	62 mm	69 mm	
Built-in I/O	None	None	None	None	16	None	None	
Ethernet function	None	None	None	None	None	Yes	None	
Loop control	None	None	None	None	None	None	50 to 300 blocks	

### Wide Selection of Unit Groups

Choose from a wide range of Units, from Basic I/O Units, Analog Units, and Position Control Units to Ethernet Units. All can be used with any of the CPU Units.

### Basic I/O Units

A wide variety of products, such as high-density mountable connectors and removable terminal blocks, is available to meet your requirements.



### **Units for Special Applications**

Units, such as the B7A, are available for interrupt inputs, quick-response inputs, and reduced I/O wiring.



### Analog, Process-control, and Temperature Control Units

24 models total

Input Units and Temperature Control Units are available to handle process data, such as temperatures, currents, and voltages. A complete lineup of models (including models with isolation between channels, high-speed models, and highprecision models) is available for a wide range of applications.



### Positioning Units

22 models total

Various Units are available for control from High-speed Counter Units to Position Control Units for open-collector and line-driver pulse outputs and EtherCAT or MECHATROLINK-II communications and Motion Control Units for applications using motion









### **Communications Units**

13 models total

Units are available for general-purpose Ethernet, as well as for data links between PLCs, and the DeviceNet and CompoNet open networks.









### Other Units

5 models total

Units such as RFID Controllers and Data Collection Units are available to meet a wide range of needs.



## Application-specific CPU Units

Achieve More Flexible and Precise Machine Control with Built-in Pulse I/O.

### **CPU Unit**



### **CPU Units with Built-in I/O**

### CJ1M-CPU2

High-speed, Flexible Programming Is Made Easy by Simply Pasting OMRON Function Blocks for Positioning.

### ■ Built-in I/O

Input interrupts: 4 points

High-speed

counter inputs: Single-phase, 100 kHz, 2 axes

or

Differential phases, 50 kHz, 2 axes

Pulse outputs: 100 kHz, 2 axes

One PWM output (CPU21)

Two PWM outputs (CPU22/CPU23)

Note: The above functions can all be used simultaneously.

■ Product	Variations
-----------	------------

Model	User memory	Data memory
CJ1M-CPU21	5 Ksteps	32 Kwords
CJ1M-CPU22	10 Ksteps	32 Kwords
CJ1M-CPU23	20 Ksteps	32 Kwords

### Input Interrupts

Up to four interrupt inputs or quick-response inputs can be used.

- For quick-response inputs, detection is possible for pulse
- Widths as short as 30 μs.
   Interrupt response uses high-speed response
- Processing at 93 μs.

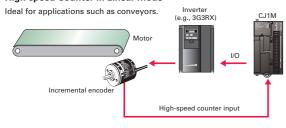
Interrupts can be created for ON signals or OFF signals.

### High-speed Counters

Up to two high-speed counter inputs can be used by connecting rotary encoders to built-in inputs.

 High-speed counting for a 24-VDC input at 60 kHz for single-phase and 30 kHz for differential phases.

### High-speed Counter in Linear Mode

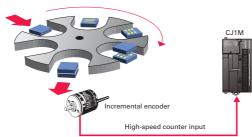


- High-speed interrupts can be processed using target value matching or zone comparison interrupts.
- The frequency (speed) can be easily measured by using a special instruction (PRV2). Ideal for applications such as measuring the speed of rotating bodies for inspections or detecting conveyer speeds. Can also be used for monitoring accumulated motor rotations.

 High-speed counting for line-driver inputs at 100 kHz for single-phase and 50 kHz for differential phases.

### **High-speed Counter in Linear Mode**

deal for applications such as electronic component index table



### **Pulse Outputs**

From stepping motors to servos, positioning control can be easily achieved using pulse outputs for one or two axes.

- Pulse output control is enabled from 1 Hz to 100 kHz.
- Startup times as fast as 46 µs reduce tact times and enable high-precision positioning.
- A high-precision variable duty ratio (PWM) can be output in 0.1% increments and used in applications such as lighting and electric power control.
- Using special instructions and OMRON Function Blocks for positioning makes programming easy even for first-time users

#### ■ Origin Search

An origin search or return operation can be executed with a single command.

- A wide range of origin search patterns is available, so the optimum origin search pattern can be selected for the machine design.
- When a Servomotor is used, position deviation is minimized by a deviation counter reset output.

#### ■ Positioning

Speed control or positioning using relative or absolute coordinates can be executed with a single command. A wide range of functions is available for positioning to suit your application.

Positioning control variations	Operation patterns	Application examples	Special instructions, OMRON Function Blocks
Trapezoidal Acceleration/ Deceleration Positioning OMRON Function Blocks and special instructions make position control easy. Detailed functions are provided for reducing out-of-step operation for stepping motors and eliminating error downtime.	Setting Acceleration     Start frequency     Setting Acceleration and Deceleration     Separately Acceleration     Securve and be set acceleration     and deceleration torrque.     S-curve Acceleration     Securve acceleration     Setting     Used to reduce vibration during high-speed positioning.     Triangular Control     Atala error does not occur even if settings do not allow the target speed to be reached.	Basic Conveyor Rail Width Positioning	Achieved with a single OMRON Function Blocks for specifying absolute (or relative) travel.  • Move Absolute (REAL) • Move Relative (REAL) • Move Relative (REAL) • Move Relative (MEAL)
Changing the Target Position during Positioning The target position can be changed during positioning. It is also possible to reverse direction when changing the target position.	Trapezoidal control (PLS2 Instruction)  Travel start  Target position (frequency, acceleration/ deceleration) changed	KS-232C  Servo Driver (e.g., SMARTSTEP 2)	While position is being controlled by a PLS2 instruction, another PLS2 instruction can be used to override the first PLS2 instruction.  • Starting Trapezoidal Control  • Starting Trapezoidal Control  • Cacccs 51  • Changing the Target Position with Another Instruction  • PLS2  • Changing the Target Position with Another Instruction
Interrupt Feeding It is possible to change to positioning control during speed control. Interrupt feeding can be executed after the interrupt for a specified number of pulses.	Speed control pulses are output and then positioning stops.  Positioning control executed	High-precision Interrupt Positioning  Sheet feeding direction  Uniform distance from detection of mark until heat welding	Achieved with a single OMRON Function Block for interrupt feeding.  • Interrupt Feeding (REAL) • Interrupt Feeding (DINT)
Sequential Positioning Travel to multiple preset points can be specified. This is effective for applications such as positioning loaders and unloaders at multiple points.		PCB Rack Positioning	Achieved with a single OMRON Function Block for specifying sequential positioning.   Achieved with a single of the sequential positioning.  Achieved the sequential positioning of the seq

## Application-specific CPU Units

Built-in Ethernet helps you handle more production site information.

Suitable for any application, from small device and loop control to large-scale control over networks.



### **CPU** with Ethernet function

## CJ1M-CPU1 ☐ -ETN

The lowest pricing level in the industry for CPU Units with built-in Ethernet.

**■ Product Variations** 

#### **■** Ethernet Functions

- FINS communications service
- FTP server
- Automatically adjusted clock information.

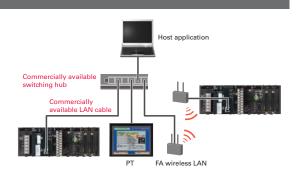
Note Socket services and sending/receiving mail are not supported.

Model	User memory	Data memory
CJ1M-CPU11-ETN	5 Ksteps	32 Kwords
CJ1M-CPU12-ETN	10 Ksteps	32 Kwords
CJ1M-CPU13-ETN	20 Ksteps	32 Kwords

#### Web functions

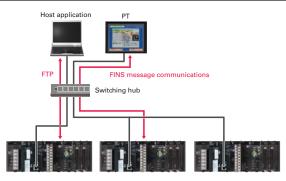
### Standard Ethernet Port

Use standard LAN cables and hubs to guickly install and connect a network.



### FTP and FINS message communications

FTP and FINS message communications can be used to freely communicate with the required devices.



### **Built-in port**

With a built-in port, the PLC can communicate with host computers without adding a special unit.





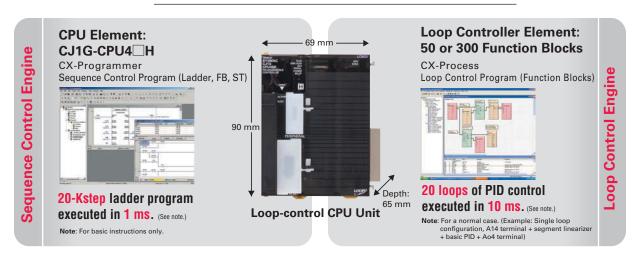
### **Loop-control CPU Units**

### CJ1G-CPU4□P CJ1G-CPU4□P-GTC

In Addition to Sequence Control, an Engine for Controlling Analog Quantities Is Built Into the CPU Unit.

### ■ Product Variations

Model	User Memory	Data Memory	Function blocks
CJ1G-CPU42P	10 Ksteps	64 Kwords	50
CJ1G-CPU43P	20 Ksteps	64 Kwords	300
CJ1G-CPU44P	30 Ksteps	64 Kwords	300
CJ1G-CPU45P	60 Ksteps	128 Kwords	300
CJ1G-CPU45P-GT0	C 60 Ksteps	128 Kwords	300

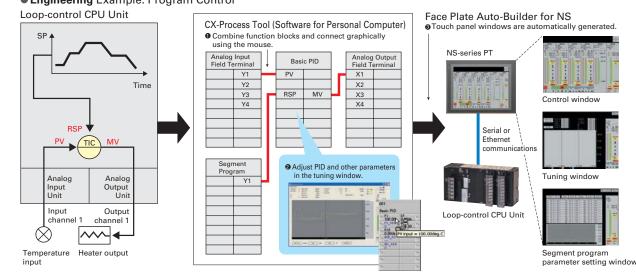


### **Easy Programming Using Function Blocks**

Programming is made easy by combining function blocks such as PID control and square root calculations and then connecting them with a mouse.

- Even complex control operations can be managed, such as program control, cascade control, and feedforward control.
- PID parameters can be adjusted on the special Tuning Screens.

### • Engineering Example: Program Control



10 11

## Function Blocks for High-quality Program Standardization and Structure

### **Function Block**

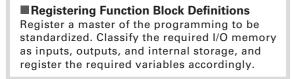
Function block support is standard for all CJ1-series CPU Units. In addition, with unit version 4.0 of the CPU Unit, functions required for standardization and structure are further improved.

### **Function Block (FB)**

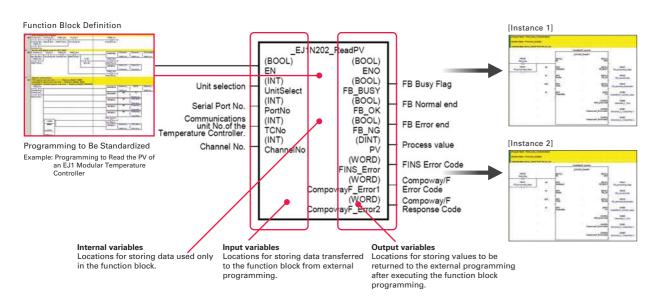
### Function blocks (FBs) are a method developed internationally for standardization of program modules.

- In contrast to the earlier subroutines and macro programs, function blocks are more easily reused and provide features that are more conducive to structured programming.
- Function blocks have spread to countries throughout the world. Although they are supported globally, local training and setting of operation rules are easy.

### **Creating Function Blocks**



■Reusing Programming (Creating Instances)
First paste the function block into the Ladder
Editor Window. Then complete the
programming by assigning input and output
variables for that function block.



### Same Debugging Functions as for Ladder Programs

- Function block internal program simulation, online corrections, and online additions are all supported.
- The efficiency of advance testing on the desktop and of debugging using actual devices is improved.



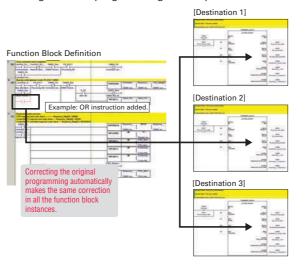
Program Display

Variable PV Display

### Program Standardization and Improved Reusability

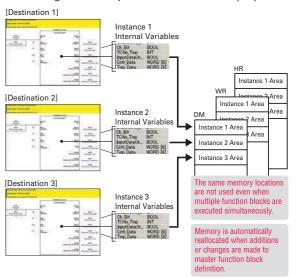
## Corrections to a function block definition are automatically reflected in all of the function block instances.

Correcting a function block definition at one place automatically makes the same correction in all the function block instances. Unlike macro programs, this prevents correction from being applied unevenly when reusing standard programming in multiple locations.



## The required internal variables are automatically created when a function block instance is created.

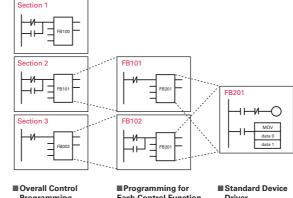
Internal variables used exclusively in the function block are automatically allocated in I/O memory. This prevents accidental access from other function blocks or programs, and prevents the same memory location from being accidentally used for two different purposes.



### A Wide Range of Functions Required for Large-scale Structured Programming

## Program nesting is supported for up to eight nesting levels.

Program nesting is required to make general-purpose low-level drivers as standard components and combine them in structured programming.



## Programming E Programming for poverall control that preceives and a

from the host.

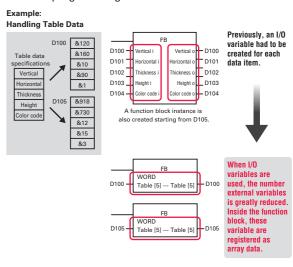
## Each Control Function Programming for each positioning control axis and communications port.

## Standard Device On Driver Programming (e.g OMRON Function

Programming (e.g., an OMRON Function Block) at the command level at the bottom of the hierarchy.

## Exchange of Large-capacity Table Data between Function Blocks (I/O Variables) (Unit Version 4.0 or Later)

I/O variable addresses can now be passed to and from function blocks. Table data, such as device recipes and control parameters, can be easily transferred from external programming to function blocks.



Note: For details on function blocks, refer to Function Block/Structured Text Introduction Guide (Cat. No. R144).

2 13

## The Optimum Programming Language for such as Device Status Changes and Numeric

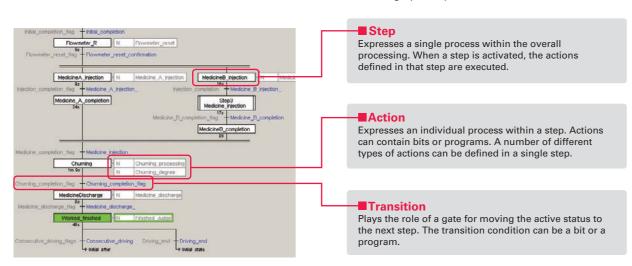
## Various Control Functions, Processing Programming Language

Expanded Support for Languages Conforming to IEC 61131-3 Standard. Greater Selection of Programming Languages for Various Applications

### Sequential Function Chart (SFC) (Unit Version 4.0 or Later)

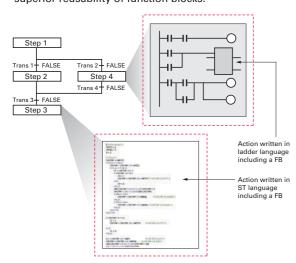
The Sequential Function Chart (SFC) language is ideal for programming changes in system status.

 SFCs can be used to express changes in overall device processes, making it easy to perform debugging and maintenance for overall system operation.  Parallel branching and joining of multiple processes executed in parallel, and conditional branching and joining of individually selected processes, can be written graphically.



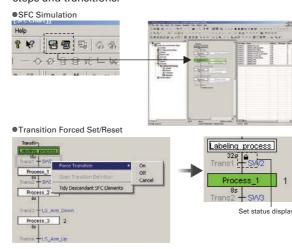
## Ladder and ST language can be used for the action and transition programs, and can include function blocks.

SFC programming can use program components structured with function blocks to take advantage of the superior reusability of function blocks.



## Superior debugging functions are supported, such as online editing and simulation.

SFC programming offers the same superior debugging functions as provided for ladder programming. In addition, forced setting and resetting are supported for steps and transitions.



Note: For details on sequential function charts, refer to SFC Introduction Guide (Cat. No. R149).

### Structured Text (ST)

Structured Text (ST) is a language developed for FA control and is effective for complex numeric and text-string processing

 Programming such as conditional branching, repeated executions, and text-string control can be written more easily than with ladder programs.

|\* Initial Settings \*)

NMTTD1 = 2

NMTTD2 = 7,

N = 2

(\* ORDITM \*) ISSEFFF;

FOR I = 1 TO N DO

CROTIMP = CROTIMP NOR NMTD1:

FOR J = 1 TO 8 DO

OT = ORDITMP \* OR THEN

OH = 1,

ORDITM = CROTIMP AND 1687FFF; (\* CROTIMP & 0.7FFF \*)

ELSE

OH = 0,

END UF,

UNIT ORDITMP = WORD, TO, UNIT (CROTIMP) / 2,

CROTIMP = UNIT TO, WORD UNIT CROTIMP) / 2,

CROTIMP = UNIT TO, WORD UNIT CROTIMP) / 2,

CROTIMP = UNIT TO, WORD UNIT CROTIMP) / 2,

CROTIMP = CROTIMP OR 1684000, (\* CROTIMP NOR 0.4000 \*)

END UF,

IF OT = 1 THEN

ORDITMP = CROTIMP NOR 1684001, (\* CROTIMP NOR 0.4001 \*)

END UF;

END FOR

END FOR

END FOR

ELSE

OL = 0,

END UF;

C1 = CROTIMP AND 1687FF; (\* CROTIMP & 0.7FFF \*)

ELSE

OL = 0,

END UF;

C1 = CROTIMP AND 1687FF; (\* CROTIMP & 0.7FFF \*)

UNIT CROTIMP = CROTIMP AND 1687FF; (\* CROTIMP & 0.7FFF \*)

UNIT CROTIMP = CROTIMP AND 1687FF; (\* CROTIMP & 0.7FFF \*)

UNIT CROTIMP = CROTIMP AND 1687FF; (\* CROTIMP & 0.7FFF \*)

UNIT CROTIMP = CROTIMP AND 1687FF; (\* CROTIMP & 0.7FFF \*)

UNIT CROTIMP = UNIT TO, UNIT CROTIMP) / 256;

C2 = UNIT TO, VORDOUNT CROTIMP)

 Because ST is a text language, maintenance and reusability are easy due to the high generality and readability.

### Example: Control Syntax

Conditional branching: IF, THEN, ELSE/CASE, ELSE
Repeated execution: FOR/WHILE loop

### **Example: Numeric Processing Functions**

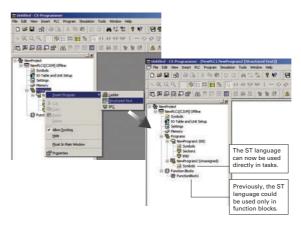
Trigonometric

functions : SIN, COS, TAN, ASIN, ACOS, ATAN

Absolute values : ABS
Logarithms : LOG, LN
Square roots : SQRT
Exponents : EXP, EXPT

### Use ST Not Only in Function Blocks But Also in Tasks (Unit Version 4.0 or Later)

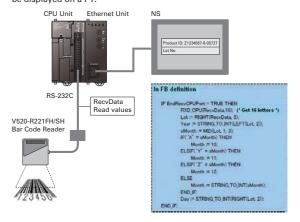
The ST language can be used according to the application, e.g., in function blocks for program standardization or in tasks for programming specific applications. The ST language can also be used to call function blocks, as well as for structuring program resources.



## Convenient for text strings used for PTs and BCR. The STRING data type is supported. (Unit version 4.0 or later)

Text string data can be written directly into programs, allowing the data to be intuitively understood.

Information stored as text strings acquired from a bar code reader can be displayed on a PT.

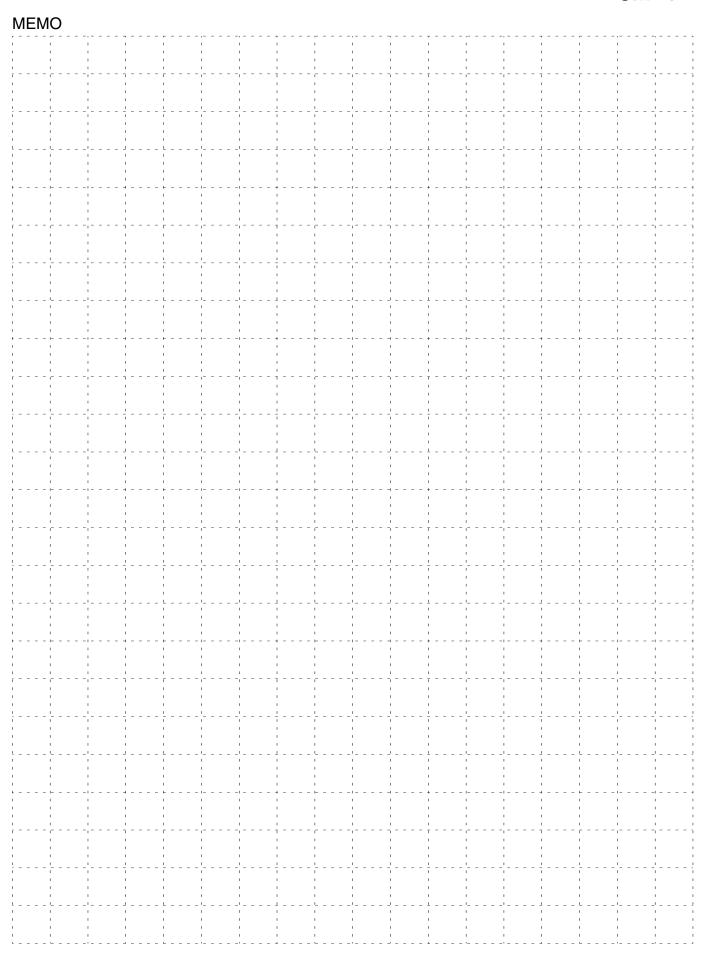


15

Note: For details on Structured Text (ST), refer to Function Block/Structured Text Introduction Guide (Cat. No. R144).

14

### OMRON

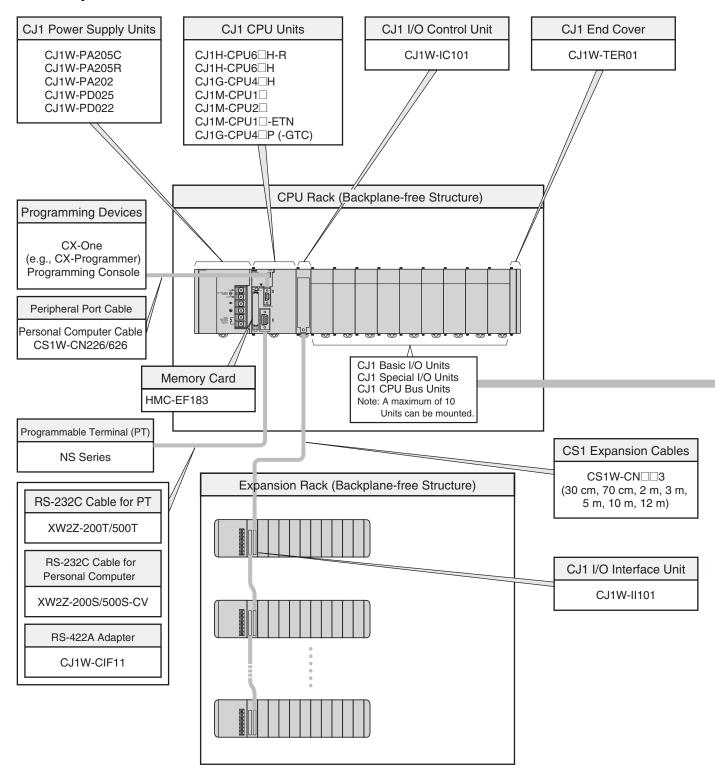


## System Design Guide

System Configuration	18
Dimensions	22
General Specifications	25
Common Specifications for CPU Units Specifications	27
CJ1M-CPU2□ (CJ1M CPU with Built-in I/O) Specifications	31
CJ1M-CPU1□-ETN (CJ1M CPU with Ethernet Function) Specifications	34
CJ1G-CPU□□P (Loop-control CPU Units) Specifications	34
Checking Current Consumption and Power Consumption	35

### **System Configuration**

### **■** Basic System



### **■** Configuration Units

CJ1 Basic I/O Units					
8-point Units	16-point Units	32-point Units	64-point Units		
	Input Units				
● DC Input Unit CJ1W-ID201 ● AC Input Unit CJ1W-IA201	● DC Input Unit CJ1W-ID211 CJ1W-ID212 High-speed type ● AC Input Unit CJ1W-IA111	DC Input Unit CJ1W-ID231 CJ1W-ID232 CJ1W-ID233 (fligh-speed type)	● DC Input Unit CJ1W-ID261 CJ1W-ID262		
	Outpu	ıt Units			
● Relay Contact Output Unit (independent commons) CJ1W-OC201 ● Transistor Output Units CJ1W-OD231 CJ1W-OD233 CJ1W-OD234 CJ1W-OD234 CJ1W-OD235 CJ1W-OD235 CJ1W-OD236 CJ1W-OD236 CJ1W-OD236 CJ1W-OD237 CJ1W-OD238 CJ1W-OD238 CJ1W-OD238 CJ1W-OD238 CJ1W-OD238 CJ1W-OD239 CJ1W-OD201 CJ1W-OD202 CJ1W-OD203 CJ1W-OD204					
	1/0	Units			
		(16 inputs, 16 outputs)  ● DC Input/Transistor Output Units CJ1W-MD231 CJ1W-MD233 CJ1W-MD232	32 inputs, 32 outputs  DC Input/Transistor Output Units CJ1W-MD261 CJ1W-MD263 32 inputs, 32 outputs  TTL I/O Unit CJ1W-MD563		
	Other Units				
	● Interrupt Input Unit CJ1W-INT01		B7A Interface Units (64 inputs) CJ1W-B7A14		
	● High-speed Input Unit CJ1W-IDP01		(64 outputs) CJ1W-B7A04 (32 inputs, 32 outputs) CJ1W-B7A22		

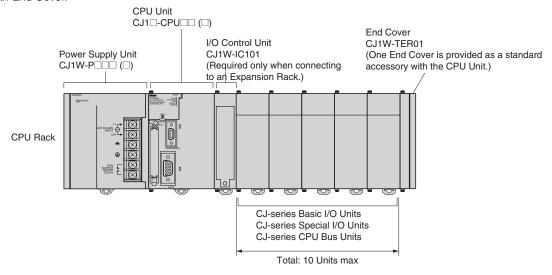
CJ1 Special I/O Units and CPU Bus Units			
■ Process I/O Units  Isolated-type Units with Universal Inputs CJ1W-PH41U CJ1W-AD04U Isolated-type Thermocouple Input Units CJ1W-PTS15 CJ1W-PTS51 Isolated-type Resistance Thermometer Input Units CJ1W-PTS52 Isolated-type DC Input Unit CJ1W-PTS52 Isolated-type DC Input Unit CJ1W-PDC15 Analog I/O Units Analog I/O Units J1W-AD041 Units CJ1W-AD041 Units CJ1W-AD041-V1 Analog Output Units CJ1W-DA08C CJ1W-DA08C CJ1W-DA08C CJ1W-DA081	■ High-speed Counter Units CJ1W-CT021 ■ Position Control Units CJ1W-NC214 High-speed type CJ1W-NC214 High-speed type CJ1W-NC414 High-speed type CJ1W-NC434 High-speed type CJ1W-NC233 CJ1W-NC213 CJ1W-NC213 CJ1W-NC233 CJ1W-NC433 ■ Position Control Unit with EtherCAT interface CJ1W-NC281 NEW CJ1W-NC281 NEW CJ1W-NC481 NEW CJ1W-NC481 NEW CJ1W-NC482 NEW CJ1W-NC482 NEW CJ1W-NC482 NEW CJ1W-NC482 NEW CJ1W-NC487 CJ1W-NC471 CJ1W-NC471 CJ1W-NC471 CJ1W-NC471 CJ1W-NCF71-MA ■ Motion Control Unit with MECHATROLINK-II interface CJ1W-NCF71 CJ1W-NCF71 CJ1W-NCF71 CJ1W-NCF71 CJ1W-NCF71 CJ1W-NCH71	■ Serial Communications Units CJ1W-SCU22 High-speed type CJ1W-SCU32 High-speed type CJ1W-SCU42 High-speed type CJ1W-SCU41-V1 CJ1W-SCU31-V1 CJ1W-SCU41-V1 ■ EtherNet/IP Unit CJ1W-EIP21 ■ Ethernet Unit CJ1W-ETN21 ■ Controller Link Units CJ1W-CLK23 ■ FL-net Unit CJ1W-FLN22 ■ DeviceNet Unit CJ1W-DRM21 ■ CompoNet Master Unit CJ1W-CRM21 ■ CompoBus/S Master Unit CJ1W-SRM21	■ ID Sensor Units CJ1W-V680C11 CJ1W-V680C12 CJ1W-V600C11 CJ1W-V600C12  ■ High-speed Data Storage Unit CJ1W-SPU01-V2

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### **■ CJ-series CPU Racks**

A CJ-series CPU Rack consists of a CPU Unit, Power Supply Unit, Configuration Units (Basic I/O Units, Special I/O Units, and CPU Bus Units), and an End Cover.



### Required Units

Rack	Unit name	Required number of Units
	Power Supply Unit	1
	CPU Unit	1
	I/O Control Unit	Required only for mounting to an Expansion Rack.
CPU Rack	Number of Configuration Units	10 max. (Same for all models of CPU Unit.) (The number of Basic I/O Units, Special I/O Units, and CPU Bus Units can be varied. The number does not include the I/O Control Unit.)
	End Cover	1 (Included with CPU Unit.)

### Types of Units

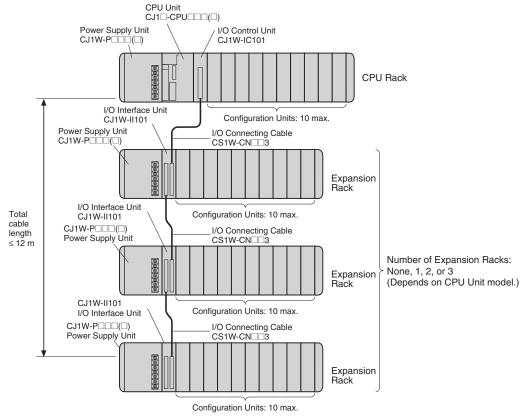
In the SYSMAC CJ Series, Units are classified into the following three types. The number of Racks differs depending on the type.

Туре	Appearance (example)	Description	Unit recognition method	No. of Units
Basic I/O Units		Basic I/O Units with contact inputs and contact outputs.	Recognized by the CPU Unit according to the position of the Rack and slot.	No restrictions.
Special I/O Units		Special I/O Units provide more advanced functions than do Basic I/O Units, including I/O other than contact inputs and contact outputs.  Examples of Special I/O Units are Analog I/O Units and High-speed Counter Units. They differ from CPU Bus Units (including Network Communications Units) in having a smaller area for exchanging data with the CPU Unit.	Recognized by the CPU Unit according to the unit number (0 to 95) set with the rotary switches on the front panel.	A maximum of 96 Units can be connected. (Multi- ple unit numbers are allo- cated per Unit, depending on the model and settings.)
CPU Bus Units	5	CPU Bus Units exchange data with the CPU Unit via the CPU Bus. Examples of CPU Bus Units are Network Communications Units and Serial Communications Units. They differ from Special I/O Units in having a larger area for exchanging data with the CPU Unit.	Recognized by the CPU Unit according to the unit number (0 to F) set with the rotary switch on the front panel.	A maximum of 16 Units can be mounted. (See note.)

Note: CJ1M-CPU1 -ETN: A Maximum of 15 Units can be mounted. (The built-in Ethernet port on the CPU Unit must be allocated as one of the CPU Bus Units)

### **■** CJ-series Expansion Racks

A CJ-series Expansion Rack consists of a Power Supply Unit, an I/O Interface Unit, Configuration Units (Basic I/O Units, Special I/O Units, and CPU Bus Units), and an End Cover.



### ■ Required Units

Rack	Unit name	Required number of Units
CPU Rack	I/O Control Unit	One Unit. Required only when an Expansion Rack is used. Mount the I/O Control Unit immediately to the right of the CPU Unit. (See note 1.)
	Power Supply Unit	One Unit
Expansion	I/O Interface Unit	One Unit. Mount the I/O Interface Unit immediately to the right of the Power Supply Unit. (See note 2.)
_ `.	Number of Configuration Units	Ten Units max. (The number of Basic I/O Units, Special I/O Units, and CPU Bus Units can be varied. This number does not include the I/O Interface Unit.)
	End Cover	One (Included with the I/O Interface Unit.)

Note 1. Mounting the I/O Control Unit in any other location may cause faulty operation.

2. Mounting the I/O Interface Unit in any other location may cause faulty operation.

### Maximum Number of Configuration Units That Can Be Mounted

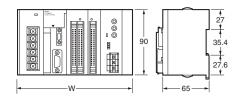
CPU Unit	Model	Total Units	No. of Units on CPU Rack	No. of Expansion Racks
CJ1H	CJ1H-CPU67H-R/67H	40	10 per Rack	3 Racks x 10 Units
	CJ1H-CPU66H-R/66H			
	CJ1H-CPU65H-R/65H			
	CJ1H-CPU64H-R			
CJ1G	CJ1G-CPU45H/45P (-GTC)			
	CJ1G-CPU44H/44P			
	CJ1G-CPU43H/43P	30	10 per Rack	2 Racks x 10 Units
	CJ1G-CPU42H/42P			
CJ1M	CJ1M-CPU13 (-ETN)	20	10 per Rack (See note.)	1 Rack x 10 Units
	CJ1M-CPU23			
	CJ1M-CPU12 (-ETN)	10	10 per Rack (See note.)	Cannot be connected.
	CJ1M-CPU11 (-ETN)			
	CJ1M-CPU22			
	CJ1M-CPU21			

Note: Up to nine Units can be connected to a CJ1M-CPU1□-ETN CPU Units. The maximum number of Configuration Units that can be connected is thus reduced by 1.

### **Dimensions**

Note: Units are in mm unless specified otherwise.

### **■** Product Dimensions

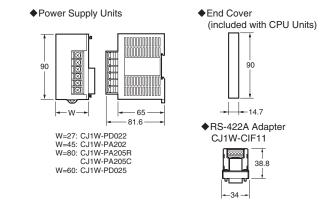


Example Rack Widths using CJ1WPA202 Power Supply Unit (AC, 14 W)

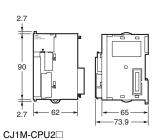
No. of	Rack width (mm)			
Units mounted with 31- mm width	With CJ1M-CPU11/ 12/13	With CJ1M-CPU21/ 22/23	With CJ1H-CPU6□H-R, CJ1H-CPU6□H, CJ1G-CPU4□H, or CJ1M-CPU1□-ETN	With CJ1G- CPU4□P(-GTC) CPU Unit
1	121.7	139.7	152.7	159.7
2	152.7	170.7	183.7	190.7
3	183.7	201.7	214.7	221.7
4	214.7	232.7	245.7	252.7
5	245.7	263.7	276.7	283.7
6	276.7	294.7	307.7	314.7
7	307.7	325.7	338.7	345.7
8	338.7	356.7	369.7	376.7
9	369.7	387.7	400.7	407.7
10	400.7	418.7	431.7	438.7

### Power Supply Units, CPU Units, and End Covers

Unit/product	Model	Width
	CJ1W-PA205C	80
	CJ1W-PA205R	80
Power Supply Unit	CJ1W-PA202	45
	CJ1W-PD025	60
	CJ1W-PD022	27
	CJ1M-CPU1□	31
	CJ1M-CPU2□	49
CPU Unit	CJ1H-CPU6□H-R CJ1H-CPU6□H CJ1G-CPU4□H CJ1M-CPU1□-ETN	62
	CJ1G-CPU4□P	69
End Cover	CJ1W-TER01	14.7



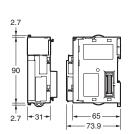




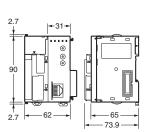
CJ1G-CPU4□P

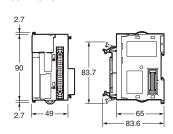


CJ1M-CPU1□



CJ1M-CPU1□-ETN

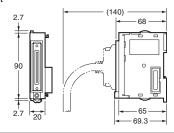


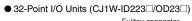


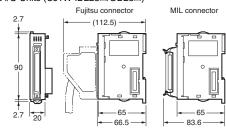
### • Units of Width 20 mm

Unit/product	Model	Width
I/O Control Unit	CJ1W-IC101	
32-point Basic I/O Units	CJ1W-ID231/232/233	
32-point basic #O offits	CJ1W-OD231/232/233/234	
	CJ1W-B7A22	20
B7A Interface Unit	CJ1W-B7A14	
	CJ1W-B7A04	
CompoBus/S Master Unit	CJ1W-SRM21	
Space Unit	CJ1W-SP001	

● I/O Control Unit





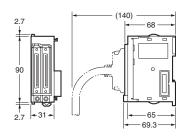


### ● Units of Width 31 mm

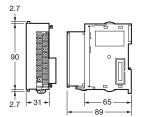
Unit	Model	Width
I/O Interface Unit	CJ1W-II101	
8/16-point Basic I/O Units	CJ1W-ID201 CJ1W-ID211/212 CJ1W-IA111/201 CJ1W-OD20 CJ1W-OD211/212/213 CJ1W-OC201/211 CJ1W-OA201	
32-point Basic I/O Units	CJ1W-MD231 CJ1W-MD232/233	
64-point Basic I/O Units	CJ1W-ID261 CJ1W-OD261 CJ1W-MD261 CJ1W-ID262 CJ1W-OD262/263 CJ1W-MD263 CJ1W-MD563	31
Interrupt Input Unit	CJ1W-INT01	
High-speed Input Unit	CJ1W-IDP01	
Analog I/O Units	CJ1W-AD□□□(-V1) CJ1W-DA□□□(□) CJ1W-MAD42	
Process Input Units	CJ1W-PH41U CJ1W-AD04U CJ1W-PTS51/52/15/16 CJ1W-PDC15	
Temperature Control Units	CJ1W-TC□□□	
Position Control Units	CJ1W-NC113/133 CJ1W-NC213/233 CJ1W-NC413/433	

Unit	Model	Width
Position Control Units with EtherCAT interface	CJ1W-NC281 CJ1W-NC481 CJ1W-NC881 CJ1W-NCF81 CJ1W-NC482 CJ1W-NC882	
Position Control Unit with MECHATROLINK-II interface	CJ1W-NC471 CJ1W-NCF71 CJ1W-NCF71-MA	
High-speed Counter Unit	CJ1W-CT021	
ID Sensor Units	CJ1W-V680C11 CJ1W-V680C12 CJ1W-V600C11 CJ1W-V600C12	31
Controller Link Units	CJ1W-CLK23	
Serial Communications Units	CJ1W-SCU22 CJ1W-SCU32 CJ1W-SCU42 CJ1W-SCU41-V1 CJ1W-SCU21-V1 CJ1W-SCU31-V1	
EtherNet/IP Unit	CJ1W-EIP21	
Ethernet Unit	CJ1W-ETN21	
DeviceNet Unit	CJ1W-DRM21	
CompoNet Master Unit	CJ1W-CRM21	
FL-net Unit	CJ1W-FLN22	

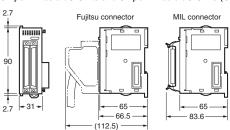
● I/O Interface Unit



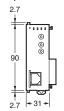
 8/6-point Basic I/O Units, Interrupt Input Unit, and Highspeed Input Unit



● 64-point Basic I/O Units and 32-point Basic I/O Units (CJ1W-MD23□)



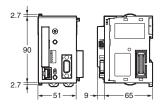
Special I/O Units and CPU Bus Units



### ● Unit of Width 51 mm

Unit	Model	Width
SYSMAC SPU (High-speed Data Storage Unit)	CJ1W-SPU01-V2	51
Position Control Units (High-speed type)	CJ1W-NC214/234	

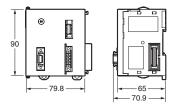
SYSMAC SPU (High-speed Data Storage Unit)
 CJ1W-SPU01-V2



### ● Unit of Width 79.8 mm

Unit	Model	Width
Motion Control Unit with MECHATROLINK-II interface	CJ1W-MCH71	79.8

 Motion Control Unit with MECHATROLINK-II interface CJ1W-MCH71



### **■** Mounting Dimensions

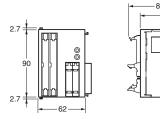


DIN Track model number	Α
PFP-100N2	16 mm
PFP-100N	7.3 mm
FPP-50N	7.3 mm

### • Unit of Width 62 mm

Unit	Model	Width
Position Control Units (High-speed type)	CJ1W-NC414/434	62

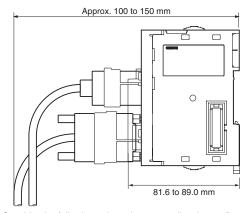
 Position Contorl Unit (High-speed model) CJ1W-NC414/434



### ■ Mounting Height

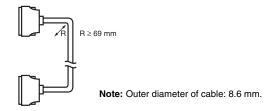
The mounting height of CJ-series CPU Racks and Expansion Racks is from 81.6 to 89.0 mm depending on the Units that are mounted.

Additional height is required to connect Programming Devices (e.g., CX-Programmer or Programming Console) and Cables. Be sure to allow sufficient mounting height.



Note: Consider the following points when expanding the configuration:
The total length of I/O Connecting Cable must not exceed 12 m.
I/O Connecting Cables require the bending radius indicated below.

### ● CJ-series Connecting Cable



### **General Specifications**

Item			Specifications		
Power Supply Unit	CJ1W-PA205R CJ1W-PA205C CJ1W-PA202		CJ1W-PD025 CJ1W-PD022		
Supply voltage	100 to 240 V AC (wide-ran	ge), 50/60 Hz		24 VDC	
Operating voltage and frequency ranges	85 to 264 V AC, 47 to 63 H	lz		19.2 to 28.8 V DC	21.6 to 26.4 V DC
Power consumption	100 VA max.		50 VA max.	50 W max.	35 W max.
Inrush current (See note 1.)	At 100 to 120 V AC: 15 A/8 ms max. for cold start at room temperature At 200 to 240 V AC: 30 A/8 ms max. for cold start at room temperature		At 100 to 120 V AC: 20 A/8 ms max. for cold start at room temperature At 200 to 240 V AC: 40 A/8 ms max. for cold start at room temperature	At 24 V DC: 30 A/20 ms max. for cold start at room temperature	
Output capacity (See note 7.)	5.0 A, 5 V DC (including st	upply to CPU Unit)	2.8 A, 5 V DC (including supply to CPU Unit) 0.4 A, 24 V DC	5.0 A, 5 V DC (including supply to CPU Unit) 0.8 A, 24 V DC	2.0 A, 5 V DC (including supply to CPU Unit) 0.4 A, 24 V DC
	Total: 25 W max.		Total: 14 W max.	Total: 25 W max.	Total: 19.6 W max.
Output terminal (service supply)	Not provided.				
RUN output (See note 2.)	Contact configuration: SPST-NO Switch capacity: 250 V AC, 2 A (resistive load) 120 V AC, 0.5 A (inductive load), 24 V DC, 2A (resistive load) 24 V DC, 2 A (inductive load)	Not provided.			
Replacement notifica- tion function	Not provided.	With Alarm output (open- collector output) 30 V DC max., 50 mA max.	Not provided.		
Insulation resistance	20 M $\Omega$ min. (at 500 V DC) between AC external and GR terminals (See note 3.)	<ul> <li>20 MΩ min. (at 500 V DC) between all external terminals and GR terminal (See note 3.), and between all alarm output terminals.</li> <li>20 MΩ 1 min. (at 250 V DC) between all alarm output terminals and GR terminal (See note 3.).</li> </ul>	20 M $\Omega$ min. (at 500 V DC) between AC external and GR terminals (See note 3.)	20 M $\Omega$ min. (at 500 V DC) between DC external and GR terminals (See note 3.)	(See note 6.)
Dielectric strength (See note 4.)			2,300 V AC 50/60 Hz for 1 min between AC external and GR terminals (See not 3.) Leakage current: 10 mA max.	1,000 V AC, 50/60 Hz for 1 minute between DC external and GR terminals (See note 3.) Leakage current: 10 mA max.	 (See note 6.)
Noise immunity	Leakage current: 10 mA m		4)		
Noise immunity  Vibration Resistance	2 kV on power supply line (conforming to IEC61000-4-4)  Conforms to IEC60068-2-6  5 to 8.4 Hz with 3.5-mm amplitude, 8.4 to 150 Hz  Acceleration of 9.8 m/s <sup>2</sup> for 100 min in X, Y, and Z directions (10 sweeps of 10 min each = 100 min total)				
Shock Resistance	Conforms to IEC60068-2-27				
Ambient operating temperature	147 m/s², 3 times in X, Y, and Z directions (100 m/s² for Relay Output Units)  0 to 55°C				
Ambient operating humidity	10% to 90% (with no condensation)	10% to 90% (with no condensation) (See note 5.)  10% to 90% (with no condensation)			
Atmosphere	Must be free from corrosive gases.				
Ambient storage temperature	-20 to 70°C (excluding battery)	-20 to 75°C (See note 5.)   -20 to 75°C (excluding battery)			
Grounding	Less than 100 Ω				
Enclosure	Mounted in a panel.				
Weight	All models are each 5 kg n	nax.			



Item	Specifications								
Power Supply Unit	CJ1W-PA205R CJ1W-PA205C CJ1W-PA202 CJ1W-PD025 CJ1W-PD022								
CPU Rack dimensions	b: CPU Unit: CJ1-H o	- 31 × m + 14.7 : PA205R and PA205C = 80 or CJ1 = 62; CJ1M-CPU1□ en by the following: W = 156	); PA202 = 45; PD025 = 60; = 31; CJ1M-CPU1□-ETN =		it I/O Units or I/O Control				
Safety measures	Conforms to cULus and E	C Directives.							

- Note 1. Disconnect the Power Supply Units LG terminal from the GR terminal when testing insulation and dielectric strength. Testing the insulation and dielectric strength with the LG terminal and the GR terminals connected will damage internal circuits in the CPU Unit.
  - 2. Supported only when mounted to CPU Rack.
  - 3. The inrush current is given for a cold start at room temperature. The inrush control circuit uses a thermistor element with a low-temperature current control characteristic. If the ambient temperature is high or the PLC is hot-started, the thermistor will not be sufficiently cool, and the inrush currents given in the table may be exceeded by up to twice the given values. When selecting fuses or breakers for external circuits, allow sufficient margin in shut-off performance.
  - 4. Maintain an ambient storage temperature of -25 to 30°C and relative humidity of 25% to 70% when storing the Unit for longer than 3 months to keep the replacement notification function in optimum working condition.
  - 5. Change the applied voltage gradually using the adjuster on the Tester. If the full dielectric strength voltage is applied or turned OFF using the switch on the Tester, the generated impulse voltage may damage the Power Supply Unit.
  - **6.** CJ1W-PD022 is not insulated between the primary DC power and secondary DC power.
  - 7. Internal components in the Power Supply Unit will deteriorate or be damaged if the Power Supply Unit is used for an extended period of time exceeding the power supply output capacity or if the outputs are shorted.

### **Specifications**

### **■** Common Specifications

	Item		Specifications					
Control method	1	Stored program						
I/O control met		Cyclic scan and immediate processing are both possil	ole.					
Programming I		Ladder Logic (LD), Sequential Function Charts (SFC), Structured Text (ST), and Mnemonic.						
CPU processin		CJ1-H CPU Units: Normal Mode, Parallel Processing Mode with Asynchronous Memory Access, Parallel Processing Mode with Synchronous Memory Access, or Peripheral Servicing Priority Mode  CJ1M CPU Units: Normal Mode or Peripheral Servicing Priority Mode  CJ1 CPU Units: Normal Mode or Peripheral Servicing Priority Mode						
Instruction len	gth	1 to 7 steps per instruction	•					
Ladder instruc		Approx. 400 (3-digit function codes)						
Execution	Basic instructions	CJ1-H-R CPU Units: CJ1-H CPU Units: CJ1M CPU Units (CPU12(-ETN)/13(-ETN)/22/23): CJ1M CPU Units (CPU11(-ETN)/21): CJ1 CPU Units:	0.016 μs min. 0.02 μs min. 0.10 μs min. 0.10 μs min. 0.08 μs min.					
time	Special instructions	CJ1-H-R CPU Units: CJ1-H CPU Units: CJ1M CPU Units (CPU12(-ETN)/13(-ETN)/22/23): CJ1M CPU Units (CPU11(-ETN)/21): CJ1 CPU Units:	0.048 μs min. 0.06 μs min. 0.15 μs min. 0.15 μs min. 0.12 μs min.					
Overhead time		CJ1-H-R CPU Units:  Normal mode: Parallel processing: CJ1-H CPU Units: 0.3 ms min Normal mode: Parallel processing: CJ1M CPU Units (CPU12(-ETN)/13(-ETN)/22/23): CJ1M CPU Units (CPU11(-ETN)/21): CJ1 CPU Units:	0.13 ms min. 0.28 ms min. 0.3 ms min. 0.3 ms min. 0.5 ms min. 0.7 ms min. 0.5 ms min. 0.5 ms min.					
Unit connection	n method	No Backplane: Units connected directly to each other.						
Mounting meth	od	DIN Track (screw mounting not possible)						
Maximum num Units	ber of connectable	<ul> <li>CJ1-H and CJ1 CPU Units:         Per CPU or Expansion Rack: 10 Units including Basic I/O Units, Special I/O Units, and CPU Bus Units.         Total per PLC: 10 Units on CPU Rack and 10 Units each on 3 Expansion Racks = 40 Units total</li> <li>CJ1M CPU Units:         Total of 20 Units in the System, including 10 Units on CPU Rack and 10 Units on one Expansion Rack.</li> <li>CJ1M CPU Units (CPU1□-ETN):         Total of 19 Units, including 9 Units on CPU Rack and 10 Units on one Expansion Rack. (The built-in Ethernet port on the CPU Unit must be allocated to a slots 0, and is counted as one Unit.</li> </ul>						
Maximum num Racks	ber of Expansion	CJ1-H and CJ1 CPU Units:  3 max. (An I/O Control Unit is required on the CPU Rack and an I/O Interface Unit is required on each Expansion Rack.)  CJ1M CPU Units (CPU 13(-ETN)/23 only):  1 max. (An I/O Control Unit is required on the CPU Rack and an I/O Interface Unit is required on the Expansion Rack.)  CJ1M CPU Units (CPU11(-ETN)/12(-ETN)/21/22): Expansion is not possible.						
Number of tasks		288 (cyclic tasks: 32, interrupt tasks: 256) With CJ1-H or CJ1M CPU Units, interrupt tasks can be defined as cyclic tasks called extra cyclic tasks. Including these, up to 288 cyclic tasks can be used.  Note 1. Cyclic tasks are executed each cycle and are controlled with TKON(820) and TKOF(821) instructions.  2. The following 4 types of interrupt tasks: are supported. Power OFF interrupt tasks: 1 max. Scheduled interrupt tasks: 2 max. I/O interrupt tasks: 32 max. External interrupt tasks: 256 max.						
Interrupt types		Scheduled Interrupts: Interrupts generated at a time scheduled by the CPU Units built-in timer. (See note. 1)  I/O Interrupts: Interrupts from Interrupt Input Units.  Power OFF Interrupts (See note 2.): Interrupts executed when the CPU Units power is turned OFF.  External I/O Interrupts: Interrupts from the Special I/O Units or CPU Bus Units.  Note 1. CJ1-H and CJ1 CPU Units: Scheduled interrupt time interval is either 1 ms to 9,999 ms or 10 ms to 99,990 ms, in units of 1 ms or 10 ms.  CJ1M CPU Units: In addition to the above, a scheduled interrupt time interval of 0.5 ms to 999.9 ms, in units of 0.1 ms, is also possible.  2. Not supported when the CJ1W-PD022 Power Supply Unit is mounted.						
Calling subroutione task	tines from more than	CJ1-H CPU Units: Supported (called global subrout     CJ1 CPU Units: Not supported.	ines).					
one task  CJ1 CPU Units: Not supported.  2,560: CIO 000000 to CIO 015915 (160 words from CIO 0000 to CIO 0159)  The setting of the first word can be changed from the default (CIO 0000) so that CIO 0000 to CIO 0999 can be used.  I/O bits are allocated to Basic I/O Units.			The CIO Area can be used as work bits if the bits are not used as					
	Link Area	3,200 (200 words): CIO 10000 to CIO 119915 (words Link bits are used for data links and are allocated to U		shown here.				

	Item				Spe	cifications					
	CPU Bus Unit Area	, ,	s): CIO 150000 to 0		•		99) er Unit, 16 Units max.)				
	Special I/O Unit Area	15,360 (960 word	ds): CIO 200000 to bits are allocated to	CIO 29591	5 (words C	IO 2000 to CIO 29	59)				
	Serial PLC Link Area (CJ1M CPU Units only)	1,440 (90 words)	1,440 (90 words): CIO 310000 to CIO 318915 (words CIO 3100 to CIO 3189)								
		9,600 (600 words DeviceNet bits ar function is used v									
		Fixed al	llocation setting 1	Outputs: Inputs:		0 to CIO 3263 0 to CIO 3363		The CIO Area can be used as work			
CIO (Core I/O)		Fixed al	llocation setting 2	Outputs: Inputs:		0 to CIO 3463 0 to CIO 3563		bits if the bits are not used as shown here.			
Area	DeviceNet Area	Fixed al	llocation setting 3	Outputs: Inputs:		0 to CIO 3663 0 to CIO 3763					
		The following wo Slave.	rds are allocated to	the Master	function e	ven when the Dev	iceNet Unit is used as a				
		Fixed al	llocation setting 1	Outputs: Inputs:		0 (Slave to Master 0 (Master to Slave	·				
		Fixed al	location setting 2	Outputs: Inputs:		O (Slave to Master O (Master to Slave	´				
		Fixed al	llocation setting 3	Outputs:		O (Slave to Master	,				
				Inputs:	CIO 367	0 (Master to Slave	)				
	Internal I/O Area	4,800 (300 words): CIO 120000 to CIO 149915 (words CIO 1200 to CIO 1499) 37,504 (2,344 words): CIO 380000 to CIO 614315 (words CIO 3800 CIO 6143) These bits in the CIO Area are used as work bits in programming to control program execution. They cannot be used for external I/O.									
Work Area		8,192 bits (512 words): W00000 to W51115 (W000 to W511)  Controls the programs only. (I/O from external I/O terminals is not possible.)  Note: When using work hits in programming, use the hits in the Work Area first before using hits from other areas									
		Note: When using work bits in programming, use the bits in the Work Area first before using bits from other areas.  8,192 bits (512 words): H00000 to H51115 (H000 to H511) Holding bits are used to control the execution of the program, and									
Holding Area		maintain their ON/OFF status when the PLC is turned OFF or the operating mode is changed.  Note: The Function Block Holding Area words are allocated from H512 to H1535. These words can be used only for the function block instance area (internally allocated variable area).									
Auxiliary Area		Read only: 7,168 bits (448 words): A00000 to A44715 (words A000 to A447) Read/write: 8,192 bits (512 words): A44800 to A95915 (words A448 to A959) Auxiliary bits are allocated specific functions.									
Temporary Are	ea	16 bits (TR0 to TR15) Temporary bits are used to temporarily store the ON/OFF execution conditions at program branches.									
Timer Area		4,096: T0000 to T4095 (used for timers only) 4.096: C0000 to C4095 (used for counters only)									
Counter Area		4,096: C0000 to C4095 (used for counters only)  32 Kwords: D00000 to D32767									
DM Area		Used as a general-purpose data area for reading and writing data in word units (16 bits). Words in the DM Area maintain their status when the PLC is turned OFF or the operating mode is changed. Internal Special I/O Unit DM Area: D20000 to D29599 (100 words × 96 Units) Used to set parameters for Special I/O Units. CPU Bus Unit DM Area: D30000 to D31599 (100 words × 16 Units) Used to set parameters for CPU Bus Units.									
EM Area (CJ1-H and CJ1 CPU Units only)		32 Kwords per bank, 7 banks max.: E0_00000 to E6_32767 max. (depending on model of CPU Unit) Used as a general-purpose data area for reading and writing data in word units (16 bits). Words in the EM Area maintain their status when the PLC is turned OFF or the operating mode is changed.  The EM Area is divided into banks, and the addresses can be set by either of the following methods. Changing the current bank using the EMBC(281) instruction and setting addresses for the current bank. Setting bank numbers and addresses directly. EM data can be stored in files by specifying the number of the first bank.									
Index Registers		IR0 to IR15 Store PLC memory addresses for indirect addressing. Index registers can be used independently in each task. One register is 32 bits (2 words).  • CJ1-H and CJ1M CPU Units: Setting to use index registers either independently in each task or to share them between tasks.									
Task Flag Area		CJ1 CPU Units: Index registers used independently in each task.  32 (TK0000 to TK0031)  Task Flags are read-only flags that are ON when the corresponding cyclic task is executable and OFF when the corresponding task is not executable or in standby status.									
Trace Memory			ce data: 31 bits, 6 w	ords)							
File Memory		Memory Cards: Compact flash memory cards can be used (MS-DOS format).     EM file memory (CJ1-H and CJ1 CPU Units only): Part of the EM Area can be converted to file memory (MS-DOS format).     OMRON Memory Cards can be used.									

### **■** Function Specifications

Item		Specifications				
Constant cycle time	1 to 32,000 ms (Unit: 1 ms)	co C Id II CDII I lait the evel of the first state of the late.				
Cycle time monitoring	Possible (Unit stops operating if the cycle is too long	r a CJ1-H CPU Unit, the instruction execution cycle is monitored. CPU Unit operation				
I/O refreshing	, ,	by IORF(097). ic I/O Units and Special I/O Units. With the CJ1-H and CJ1M CPU Units, the CPU BUS can be used to refresh bits allocated to CPU Bus Units in the CIO and DM Areas.				
Timing of special refreshing for CPU Bus Units	Units is performed at the following times:  • CJ1 and CJ1M CPU Units: I/O refresh period	NK Units, remote I/O for DeviceNet Units, and other special refreshing for CPU Bus are CPU BUS UNIT I/O REFRESH (DLNK(226)) instruction is executed.				
I/O memory holding when changing operating modes	Depends on the ON/OFF status of the IOM Hold Bit	in the Auxiliary Area.				
Load OFF	All outputs on Output Units can be turned OFF whe	n the CPU Unit is operating in RUN, MONITOR, or PROGRAM mode.				
Timer/Counter PV refresh method	CJ1-H and CJ1M CPU Units: BCD or binary (CX-Pr CJ1 CPU Units: BCD only.					
Input response time setting	Time constants can be set for inputs from Basic I/O The time constant can be increased to reduce the ir inputs.	Units.  fluence of noise and chattering or it can be decreased to detect shorter pulses on the				
Mode setting at power-up	Possible.  Note: By default, the CPU Unit will start in RUN mo	de if a Programming Console is not connected.				
Flash memory (CJ1-H and CJ1M CPU Units only)	and restore.)  CPU Units with unit version 3.0 or later only: When downloading projects from CX-Programme comments), comment files (CX-Programmer rung	, PLC Setup) are always backed up automatically in flash memory. (automatic backup er Ver. 5.0 or higher, symbol table files (including CX-Programmer symbol names, I/O g comments, other comments), and program index files (CX-Programmer section s) are stored in comment memory within the flash memory.				
	Automatically reading programs (autoboot) from the Memory Card when the power is turned ON.	Possible.				
	Program replacement during PLC operation	Possible.				
Memory Card functions	Format in which data is stored in Memory Card	User program: Program file format PLC Setup and other parameters: Data file format I/O memory: Data file format (binary format), text format, or CSV format				
	Functions for which Memory Card read/write is supported	User program instructions, Programming Devices (including CX-Programmer and Programming Consoles), Host Link computers, AR Area control bits, easy backup operation				
Filing	Memory Card data and the EM (Extended Data Mer	mory) Area can be handled as files.				
Debugging	Control set/reset, differential monitoring, data tracing storing location generating error when a program er	g (scheduled, each cycle, or when instruction is executed), instruction error tracing,				
Online editing		units when the CPU Unit is in MONITOR or PROGRAM mode. areas.				
Program protection	Overwrite protection: Set using DIP switch. Copy protection: Password set using CX-Programm					
Error check	User-defined errors (i.e., user can define fatal errors The FPD(269) instruction can be used to check the <b>Note:</b> FAL and FALS instructions can be used with	execution time and logic of each programming block.				
Error log		on includes the error code, error details, and the time the error occurred. at user-defined FAL errors are not stored in the error log.				
Serial communications	(CompoWay/F master)	ling Programming Console) connections, Host Links, NT Links, Serial Gateway ling Programming Console) connections, Host Links, no-protocol communications, NT Way/F master or Modbus master)				
	Serial Communications Unit (sold separately): Protocol macros, Host Links, NT Links  Provided on all models.					
		nthly error				
Clock		to +0.5 min				
	25°C -1.5 min to +1.5 min 0°C -3 min to +1 min					
Power OFF detection	AC Power Supply Unit: 10 to 25 ms (not fixed)					
Power OFF detection	DC Power Supply Unit PD025: 2 to 5 ms; PD022: 2  0 to 10 ms (user-defined, default: 0 ms)					
delay time	Note: Not supported when the CJ1W-PD022 Power	r Supply Unit is mounted.  and Extended Data Memory, and status of the counter Completion Flags and present				
Memory protection	values.  Note: If the IOM Hold Bit in the Auxiliary Area is tur	rned ON, and the PLC Setup is set to maintain the IOM Hold Bit status when power to D Area, the Work Area, part of the Auxiliary Area, timer Completion Flag and PVs, Index				
Sending commands to a Host Link computer	FINS commands can be sent to a computer connect the PLC.	ted via the Host Link System by executing Network Communications Instructions from				



Item	Specifications
Remote program- ming and monitoring	Host Link communications can be used for remote programming and remote monitoring through a Controller Link System or Ethernet network.
Communicating across network levels	Remote programming and monitoring from Support Software and FINS message communications can be performed across different network levels, even for different types of network.  Pre-Ver. 2.0: Three levels  Version 2.0 or later: Eight levels for Controller Link and Ethernet networks (See note.), three levels for other networks.  Note: To communicate across eight levels, the CX-Integrator or the CX-Net in Programmer version 4.0 or higher must be used to set the routing tables.
Storing comments in CPU Unit	I/O comments can be stored as symbol table files in the Memory Card, EM file memory, or comment memory (see note). Note: Comment memory is supported for CX-Programmer version 5.0 or higher and CS/CJ-series CPU Units with unit version 3.0 or later only.
Program check	Program checks are performed at the beginning of operation for items such as no END instruction and instruction errors. CX-Programmer can also be used to check programs.
Control output signals	RUN output: The internal contacts will turn ON (close) while the CPU Unit is operating (CJ1W-PA205R).
Battery life	Battery Set for CJ1-H and CJ1 CPU Units: CPM2A-BAT01     Battery Set for CJ1M CPU Units: CJ1W-BAT01
Self-diagnostics	CPU errors (watchdog timer), I/O bus errors, memory errors, and battery errors.
Other functions	Storage of number of times power has been interrupted. (Stored in A514.)

### ● Functions Added for New Unit Versions

Refer to the SYSMAC CJ-series CJ1 CPU Units Datasheet.

### ● Relations between CX-Programmer Versions and Unit Versions of CPU Units

Refer to the SYSMAC CJ-series CJ1 CPU Units Datasheet.

### CJ1M-CPU2□ (CJ1M CPU with Built-in I/O) Specifications

- CJ1M-CPU2 CPU Units have 10 built-in inputs and 6 built-in outputs.
- The 10 inputs can be used as general-purpose inputs, interrupt inputs, quick-response inputs, high-speed counters, or origin search origin input signals.
- The 6 outputs can be used as general-purpose outputs, pulse outputs, or origin search deviation counter reset outputs.

### ■ Data Area Allocations for Built-in I/O

	I/O Co	de	IN 0	IN 1	IN 2	IN 3	IN 4	IN 5	IN 6	IN 7	IN 8	IN 9	OUT 0	OUT 1	OUT 2	OUT 3	OUT 4	OUT 5
Address		2960										2961						
Bit			0	1	2	3	4	5	6	7	8	9	0	1	2	3	4	5
	Genera	al se inputs	General purpose input 0	General purpose input 1	General purpose input 2	General purpose input 3	General pur- pose input 4	General pur- pose input 5	General pur- pose input 6	General pur- pose input 7	General pur- pose input 8	General pur- pose input 9						
	Interru	pt inputs	Interrupt input 0	Interrupt input 1	Interrupt input 2	Interrupt input 3												
	Quick inputs	response	Quick response input 0	Quick response input 1	Quick response input 2	Quick response input 3												
inputs	High-s				High- speed counter 1 (phase- Z/reset)	High- speed counter 0 (phase- Z/reset)			High- speed counter 1 (phase- A, incre- ment, or count input)	High- speed counter 1 (phase- B, dec- rement, or direc- tion input)	High- speed counter 0 (phase- A, incre- ment, or count input)	High- speed counter 0 (phase- B, dec- rement, or direc- tion input)						
	Genera pose o	al-pur- outputs											Gen- eral- pur- pose output 0	Gen- eral- pur- pose output 1	Gen- eral- pur- pose output 2	Gen- eral- pur- pose output 3	Gen- eral- pur- pose output 4	Gen- eral- pur- pose output 5
Out-		CW/CCW outputs											Pulse output 0 (CW)	Pulse output 0 (CCW)	Pulse output 1 (CW)	Pulse output 1 (CCW)		
puts	Pulse out- puts	Pulse + direction outputs											Pulse output 0 pulse)	Pulse output 1 (pulse)	Pulse output 0 (direc- tion)	Pulse output 1 (direc- tion)		
		Variable duty ratio outputs															PWM(8 91) out- put 0	PWM(8 91) out- put 1
Origin search		Origin search 0 (Origin Input Signal)	Origin search 0 (Origin Proxim- ity Input Signal)	Origin search 1 (Origin Input Signal)	Origin search 1 (Origin Proxim- ity Input Signal)	Origin search 0 (Posi- tioning Com- pleted Signal)	Origin search 1 (Posi- tioning Com- pleted Signal)									Origin search 0 (Error Counter Reset Output)	Origin search 1 (Error Counter Reset Output)	

Note: CJ1M-CPU21 CPU Units have one PWM output only and do not have PWM output 1.

### **■** Built-in Input Specifications

### ● Interrupt Inputs and Quick-response Inputs

Item		Specifications
No. of interrupt inputs/ quick-response inputs		4 total
Input inter-	Direct (Input Interrupt) Mode	Execution of an interrupt task is started at the interrupt input's rising or falling edge. Interrupt numbers 140 to 143 are used (fixed). Response time from meeting input condition to start of interrupt task execution: 93 μs min.
rupts	High-speed Counter Mode	Rising or falling edges of the interrupt are counted using either an incrementing or decrementing counter, and an interrupt task is started when the input count reaches the set value. Interrupt numbers 140 to 143 are used (fixed). I/O response frequency: 1 kHz
Quick-response inputs		Signals that are shorted than the cycle time (30 µs min.) can be read and treated the same as signals that are one for more than one cycle time.

### High-speed Counter Inputs

		<u> </u>							
	Item	Specifications							
Number of counters	high-speed	2 (High-speed counters 0 and 1)							
Pulse input in PLC Setu	mode (Selected up)	I I I I I I I I I I I I I I I I I I I		Pulse + direction inputs (pulse inputs, direction inputs, reset inputs)	Increment inputs (increment inputs, reset inputs)				
Re- sponse	Line-driver inputs	50 kHz	100 kHz	100 kHz	100 kHz				
frequency	24-V DC inputs	30 kHz	60 kHz	60 kHz	60 kHz				
Counting mode		Linear mode or Ring mode (Select in the PLC Setup.)							

	Item	Specifications				
Count value		Linear mode: 80000000 to 7FFFFFFF hex Ring mode: 00000000 to Ring SV (The Ring SV is set in the PLC Setup and the setting range is 00000001 to FFFFFFFF hex.)				
High-speed counter PV storage locations		High-speed counter 0: A271 (leftmost 4 digits) and A270 (rightmost 4 digits) High-speed counter 1: A273 (leftmost 4 digits) and A272 (rightmost 4 digits) Target value comparison interrupts or range comparison interrupts can be executed based on these PVs.  Note: The PVs are refreshed in the overseeing processes at the beginning of each cycle. Use the PRV(881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most received by the PRV (881) instruction to read the most recei				
Control	Target value comparison	Up to 48 target values and corresponding interrupt task numbers can be registered.				
method	Range comparison	Up to 8 ranges can be registered, with an upper limit, lower limit, and interrupt task number for each.				
Counter reset method		Phase-Z + Software reset: Counter is reset when phase-Z input goes ON while Reset Bit is ON. Software reset: Counter is reset when Reset Bit goes ON. Reset Bits: High-speed Counter 0 Reset Bit is A53100, Counter 1 Reset Bit is A53101.				

## ■ Built-in Output Specifications • Position Control and Speed Control

Item	Specifications
Number of pulse outputs	2 (Pulse output 0 or 1)
Output frequency	1 Hz to 100 kHz (1-Hz units from 1 to 100 Hz, 10-Hz units from 100 Hz to 4 kHz, and 100-Hz units from 4 to 100 kHz)
Frequency acceleration and deceleration rates	Set in 1 Hz units for acceleration/deceleration rates from 1 Hz to 2 kHz (every 4 ms). The acceleration and deceleration rates can be set separately only with PLS2(887).
Changing SVs during in- struction execution	The target frequency, acceleration/deceleration rate, and target position can be changed. Changes to the target frequency and acceleration/deceleration rate must be made at constant speed.
Pulse output method	CW/CCW inputs or Pulse + direction inputs
Number of output pulses	Relative coordinates: 00000000 to 7FFFFFF hex (Each direction accelerating or decelerating: 2,147,483,647) Absolute coordinates: 80000000 to 7FFFFFFF hex (-2,147,483,648 to 2,147,483,647)
Instruction used for origin searches and returns	ORIGIN SEARCH (ORG(889)): Origin search and origin return operations according to set parameters
Instructions used for position and speed control	PULSE OUTPUT (PLS2(887)): Trapezoidal output control with separate acceleration and deceleration rate SET PULSES (PULS(886)): Setting the number of pulses for pulse output SPEED OUTPUT (SPED(885)): Pulse output without acceleration or deceleration (Number of pulses must be set in advance with PULS(886) for position control.) ACCELERATION CONTROL (ACC(888)): Changes frequency or pulse output with acceleration and deceleration MODE CONTROL (INI(880)): Stopping pulse output
Pulse output PV's storage location	The following Auxiliary Area words contain the pulse output PVs: Pulse output 0: A277 (leftmost 4 digits) and A276 (rightmost 4 digits) Pulse output 1: A279 (leftmost 4 digits) and A278 (rightmost 4 digits) The PVs are refreshed during regular I/O refreshing. PVs can be read to user-specified words with the PRV(881) instruction.

### ● Variable-duty Pulse Outputs (PWM)

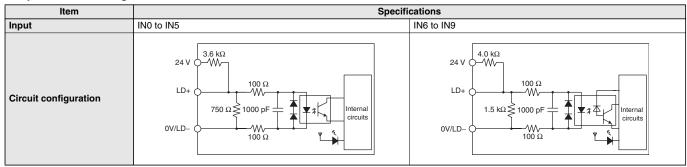
Item	Specifications
Number of PWM outputs	CJ1M-CPU22/23: 2 (PWM output 0 or 1) CJ1M-CPU21: 1 (PWM output 0)
Duty ratio	0% to 100%, set in 0.1% units (See note.)
Frequency	0.1 Hz to 999.9 Hz, Set in 0.1 Hz units.
Instruction	PULSE WITH VARIABLE DUTY RATIO (PWM(891)): Sets duty ratio and outputs pulses.

 $\textbf{Note:} \ \text{CJ1M CPU Unit Ver. 2.0 or later only. } (0\% \ \text{to } 100\%, \text{set in } 1\% \ \text{units for Pre-Ver. 2.0 CPU Units.})$ 

## ■ Hardware Specifications• Input Specifications

Ite	em	Specifications								
Number of in	puts	10 inputs	0 inputs							
Input method		24-V DC inputs or line driver (wi	ring changed to select)							
Input voltage	specifica-	24 V DC		Line driver						
tions		IN0 to IN5	IN6 to IN9	IN0 to IN5	IN6 to IN9					
Input voltage		20.4 to 26.4 V DCV		RS-422A or RS-422 line driver (conforming to AM26LS31), Power supply voltage of 5 V ± 5%						
Input impeda	nce	3.6 kΩ	4.0 kΩ							
Input current	(typical)	6.2 mA	4.1 mA	13 mA	10 mA					
Minimum Ol	N voltage	17.4 V DC/3 mA min.								
Maximum OF	F voltage	5.0 V DC/1 mA max.								
Response speed (for	ON re- sponse time	Default setting: 8 ms max. (The input time constant can be set to 0 ms, 0.5 ms, 1 ms, 2 ms, 4 ms, 8 ms, 16 ms, or 32 ms in the PLC Setup.)								
general-pur- pose inputs)	OFF re- sponse time	Default setting: 8 ms max. (The Setup.)	input time constant can be set to	0 ms, 0.5 ms, 1 ms, 2 ms, 4 ms, 8	8 ms, 16 ms, or 32 ms in the PLC					

### ● Input Circuit Configuration



### ● General-purpose Output Specifications for Transistor Outputs (Sinking)

	-						
Item	Specifications						
Output	OUT0 to OUT3 OUT4 to OUT5						
Rated voltage	5 to 24 V DC						
Allowable voltage range	4.75 to 26.4 V DC						
Max. switching capacity	0.3 A/output; 1.8 A/Unit						
Number of circuits	6 outputs (6 outputs/common)						
Max. inrush current	3.0 A/output, 10 ms max.						
Leakage current	0.1 mA max.						
Residual voltage	0.6 V max.						
ON delay	0.1 mA max.						
OFF delay	0.1 mA max.						
Fuse	None						
External power supply	10.2 to 26.4 V DC 50 mA min.						
Circuit configuration	COM  Low voltage circuit  to OUT3  COM  COM  COM						

### ● Pulse Output Specifications (OUT0 to OUT3)

Item	Specifications			
Max. switching capacity	30 mA, 4.75 to 26.4 V DC			
Min. switching capacity	7 mA, 4.75 to 26.4 V DC			
Max. output frequency	100 kHz			
Output waveform	OFF 90%			

### CJ1M-CPU1□-ETN (CJ1M CPU with Ethernet Function) Specifications

These CPU Units provide built-in Ethernet functionality.

### Ethernet Functional Element Transfer Specifications

Item		Specification		
Media access method		CSMA/CD		
Modulation method		Baseband		
Transmission paths		Star form		
Baud rate		100 Mbit/s (100Base-TX), 10 Mbit/s (10Base-T)		
Transmission media	100 Mbit/s	Unshielded twisted-pair (UDP) cable Categories: 5, 5e Shielded twisted-pair (STP) cable Categories: 100 $\Omega$ at 5, 5e		
Transmission media	10 Mbit/s	Unshielded twisted-pair (UDP) cable Categories: 3, 4, 5, 5e Shielded twisted-pair (STP) cable Categories: 100 $\Omega$ at 3, 4, 5, 5e		
Transmission distance		100 m (distance between hub and node)		
Number of cascade connections		There are no restrictions with the use of switching hubs.		
CPU Bus Unit System Se	etup Area capacity	994 bytes (See note 2.)		

Note: The system settings for Ethernet are in the CPU Bus Unit System Setup Area in the CPU Unit.

### CJ1G-CPU□□P (Loop-control CPU Units) Specifications

In addition to engines for executing sequence control, Loop-control CPU Units (CJ1G-CPU□□P) have built-in engines for controlling analog quantities (such as temperatures, pressure and flow rate), thus enabling high-speed sequence control and advanced high-speed control of analog quantities in a single Unit.

### CPU Element (Sequence Control)

Name	I/O bits	Program capacity	DM words	EM words	Model
				32K words × 3 banks	CJ1G-CPU45P
Loop control CDLLInit	1,280 bits 960 bits	60K steps	32K words	E0_00000 to E2_32767	CJ1G-CPU45P-GTC (See note.)
Loop-control CPU Unit		30K steps		32K words × 1 bank E0 00000 to E0 32767	CJ1G-CPU44P
		20K steps			CJ1G-CPU43P
		10K steps		20_00000 to 20_02707	CJ1G-CPU42P

Note: These Loop-control CPU Units support gradient temperature control, a technology for uniform in-plane control of temperatures of plane-shaped objects (e.g., multi-point control of surface temperatures based on a multi-point heater). For details, please contact an OMRON representative.

### ● Loop Controller Element (Loop Control)

Item		Model	CJ1G-CPU42P	CJ1G-CPU43P	CJ1G-CPU44P	CJ1G-CPU45P(-GTC)		
Operation	method		Function block method	Function block method				
Operation cycle			0.01, 0.02, 0.05, 0.1, 0.2, 0.5, 1, or 2 s (default: 1 s) Can be set for each function block.					
	Analog operations	Control and opera- tion blocks	50 blocks max.	50 blocks max. 300 blocks max.				
Number	Sequence control	Step ladder program blocks	20 blocks max. 2,000 commands total	200 blocks max 4 000 commands total				
of func- tion blocks	I/O blocks	Field terminal blocks	30 blocks max.		40 blocks max.			
DIOCKS	I/O DIOCKS	User link tables	2,400 data items max.					
		Batch allocation	HMI function, allocated 1 EM Area bank					
	System Com	mon block	Single block					
Method fo blocks	r creating and	transferring function	Created using CX-Process Tool (order separately) and transferred to Loop Controller.					
	PID control m	nethod	PID with 2 degrees of freedom (with autotuning)					
Control method Control combinations			Any of the following function blocks can be combined:  Basic PID control, cascade control, feed-forward control, sample PI control, Smith dead time compensation control, PID control with differential gap, override control, program control, time-proportional control, etc.					
Alarms	Alarms PID block internal alarms		4 PV alarms (upper upper-limit, upper limit, lower limit, lower lower-limit) and 1 deviation alarm per PID block.					
Aidillis	Alarm blocks		High/low alarm blocks, deviation alarm blocks					

### **Checking Current Consumption and Power Consumption**

After selecting a Power Supply Unit based on considerations such as the power supply voltage, calculate the current and power requirements for each Rack.

Condition 1: Current Requirements

There are two voltage groups for internal power consumption: 5 V and 24 V.

Current consumption at 5 V (internal logic power supply)

Current consumption at 24 V (relay driving power supply)

Condition 2: Power Requirements

For each Rack, the upper limits are determined for the current and power that can be provided to the mounted Units. Design the system so that the total current consumption for all the mounted Units does not exceed the maximum total power or the maximum current supplied for the voltage groups shown in the following tables.

The maximum current and total power supplied for CPU Racks and Expansion Racks according to the Power Supply Unit model are shown below

Note 1. For CPU Racks, include the CPU Unit current and power consumption in the calculations. When expanding, also include the current and power consumption of the I/O Control Unit in the calculations.

2. For Expansion Racks, include the I/O Interface Unit current and power consumption in the calculations.

	Max. cur	Max. total		
Power Supply Units	5 V	24 V (relay driv- ing current)	power sup- plied	
CJ1W-PA205C	5.0 A	0.8 A	25 W	
CJ1W-PA205R	5.0 A	0.8 A	25 W	
CJ1W-PA202	2.8 A	0.4 A	14 W	
CJ1W-PD025	5.0 A	0.8 A	25 W	
CJ1W-PD022	2.0 A	0.4 A	19.6 W	

Conditions 1 and 2 below must be satisfied.

Condition 1: Maximum Current

- (1) Total Unit current consumption at 5 V  $\leq$  (A) value
- (2) Total Unit current consumption at 24 V  $\leq$  (B) value

Condition 2: Maximum Power

 $(1) \times 5 \text{ V} + (2) \times 24 \text{ V} \leq (C) \text{ value}$ 

### **■** Example: Calculating Total Current and Power Consumption

Example: When the Following Units are Mounted to a CJ-series CPU Rack Using a CJ1W-PA202 Power Supply Unit

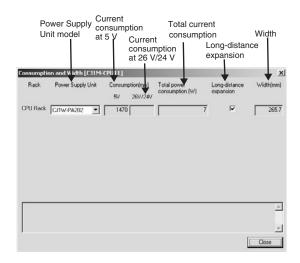
Unit type	Model	Quantity	Voltage group				
Onit type	Wodei	Quantity	5 V	24 V			
CPU Unit	CJ1G-CPU45H	1	0.910 A				
I/O Control Unit	CJ1W-IC101	1	0.020 A				
Basic I/O Units (Input Units)	CJ1W-ID211	2	0.080 A				
Basic I/O Offits (Input Offits)	CJ1W-ID231	2	0.090 A				
Basic I/O Units (Output Units)	sic I/O Units (Output Units) CJ1W-OC201		0.090 A	0.048 A			
Special I/O Unit	CJ1W-DA041	1	0.120 A				
CPU Bus Unit	CJ1W-CLK23	1	0.350 A				
Current consumption	Total		0.910 + 0.020 + 0.080 × 2 + 0.090 × 2 + 0.090 × 2 + 0.120 + 0.350	0.048 A × 2			
	Result		1.92 A (≤ 2.8 A)	0.096 A (≤ 0.4 A)			
Power consumption	Total		1.92 × 5 V = 9.60 W	0.096 A × 24 V = 2.304 W			
Power consumption	Result		9.60 + 2.304 = 11.904 W (≤ 14 W)				

Note: For details on Unit current consumption, refer to Ordering Information.

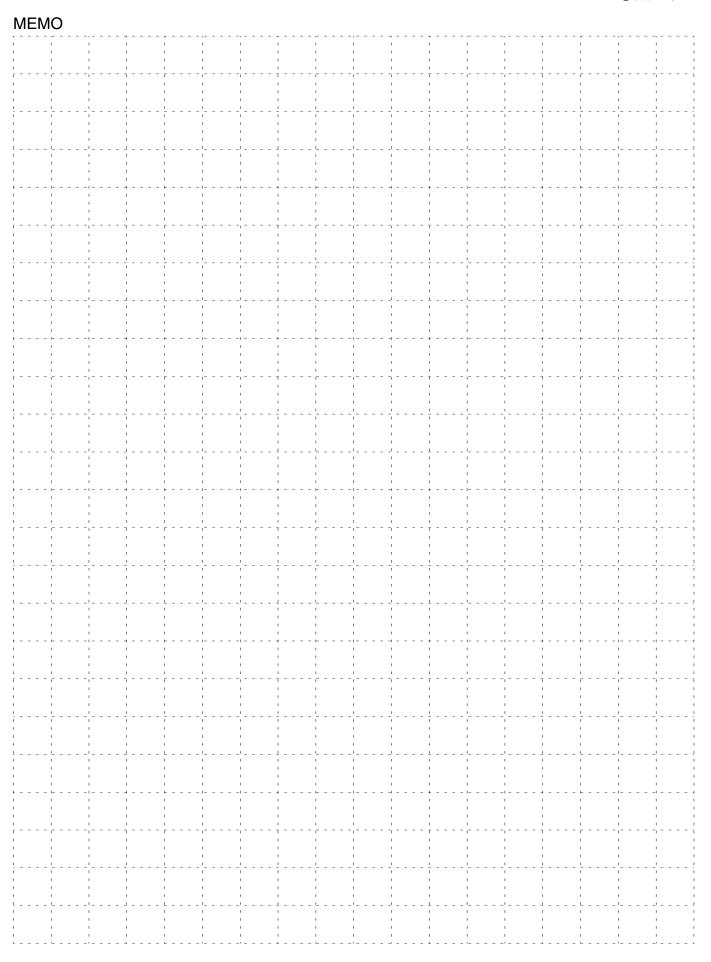
### ■ Using the CX-Programer to Display Current Consumption and Width

CPU Rack and Expansion Rack current consumption and width can be displayed by selecting Current Consumption and Width from the Options Menu in the CS/CJ/CP Table Window. (The width can be displayed for the CJ/CP Series only.) If the capacity of the Power Supply Unit is exceeded, it will be displayed in red characters. For details, refer to the *CX-Programmer Operation Manual* (Cat. No. W446).

#### Example:



### OMRON



## Ordering Information

Basic Configuration Units	38
Programming Devices	42
Optional Products and Maintenance Products	46
DIN Track Accessories	46
Basic I/O Units	47
Special I/O Units and CPU Bus Units	51

### International Standards

- The standards are abbreviated as follows: U: UL, U1: UL (Class I Division 2 Products for Hazardous Locations), C: CSA, UC: cULus, UC1: cULus (Class I Division 2 Products for Hazardous Locations), CU: cUL, N: NK, L: Lloyd, and CE: EC Directives.
- Contact your OMRON representative for further details and applicable conditions for these standards.

### EC Directives

The EC Directives applicable to PLCs include the EMC Directives and the Low Voltage Directive. OMRON complies with these directives as described below.

EMC Directives

Applicable Standards

EMI: EN61000-6-4, EN61131-2

EMS: EN61000-6-2, EN61131-2

PLCs are electrical devices that are incorporated in machines and manufacturing installations. OMRON PLCs conform to the related EMC standards so that the devices and machines into which they are built can more easily conform to EMC standards. The actual PLCs have been checked for conformity to EMC standards. Whether these

standards are satisfied for the actual system, however, must be checked by the customer.

EMC-related performance will vary depending on the configuration, wiring, and other conditions of the equipment or control panel in which the PLC is installed. The customer must, therefore, perform final checks to confirm that the overall machine or device conforms to EMC standards.

### ■ Low Voltage Directive

Applicable Standard: EN61131-2

VDC must satisfy the appropriate safety requirements. With PLCs, this applies to Power Supply Units and I/O Units that operate in these voltage ranges.

These Units have been designed to conform to EN61131-2, which is the applicable standard for PLCs.

### **Ordering Information**

### **Basic Configuration Units**

**CPU Units** 

### **■ CJ1 CPU Units**

		Spe	ecifications	Current consumption (A)				
Product name	Mountable Units Program Data memory canacity instruction		instruction execution	5 V 24 V		Model	Standards	
		250K steps	448K words (DM: 32K words, EM: 32K words × 13 banks)		0.99 (See note 1.)		CJ1H-CPU67H-R	
CJ1-H-R CPU Units	2,560 points/ 40 Units	120K steps	256K words (DM: 32K words, EM: 32K words × 7 banks)		0.99 (See note 1.)		CJ1H-CPU66H-R	UC1, N, L,
	(3 Expansion Racks max.)	60K steps	128K words (DM: 32K words, EM: 32K words × 3 banks)	- 0.016 μs	0.99 (See note 1.)		CJ1H-CPU65H-R	CE
		30K steps	64K words (DM: 32K words, EM: 32K words × 1 bank)		0.99 (See note 1.)		CJ1H-CPU64H-R	
CJ1H-H CPU Units		250K steps	448K words (DM: 32K words, EM: 32K words × 13 banks)		0.99 (See note 1.)		CJ1H-CPU67H	UC1, N, L,
	2,560 points/ 40 Units (3 Expansion Racks max.)	120K steps	256K words (DM: 32K words, EM: 32K words × 7 banks)	0.02 μs	0.99 (See note 1.)		CJ1H-CPU66H	
29		60K steps	128K words (DM: 32K words, EM: 32K words × 3 banks)		0.99 (See note 1.)		CJ1H-CPU65H	
	1,280 points/ 40 Units	60K steps	128K words (DM: 32K words, EM: 32K words × 3 banks)		0.91 (See note 1.)		CJ1G-CPU45H	
CJ1G-H CPU Units	(3 Expansion Racks max.)	30K steps		0.04 μs	0.91 (See note 1.)		CJ1G-CPU44H	UC1, N, L,
	960 points/ 30 Units	20K steps	64K words (DM: 32K words, EM: 32K words × 1 bank)	0.04 μs	0.91 (See note 1.)		CJ1G-CPU43H	CE
	(2 Expansion Racks max.)	10K steps			0.91 (See note 1.)		CJ1G-CPU42H	
Without built-in I/O	640 points/ 20 Units (1 Expansion Racks max.)	20K steps			0.58 (See note 1.)		CJ1M-CPU13	
CJ1M CPU Units	320 points/ 10 Units (No Expansion Rack)	10K steps	32 K words (DM: 32K words, EM: None)	0.1 μs	0.58 (See note 1.)		CJ1M-CPU12	UC1, N, L, CE
	160 points/ 10 Units (No Expansion Rack)	5K steps			0.58(See note 1.)		CJ1M-CPU11 (See note 2.)	

Note 1. Current consumptions include current for a Programming Console. Add 0.15 A per Adapter when using NT-AL001 RS-232C/RS-232A Adapters. Add 0.04 A per Adapter when using CJ1W-CIF11 RS-422A Adapters.

<sup>2.</sup> The CJ1M low-end models (CJ1M-CPU11(-ETN)/CPU21) have different specifications for the overhead processing time, pulse start time, number of subroutines, number of jumps, number of scheduled interrupts, and number of PWM outputs than the other CJ1M models (CJ1M-CPU12(-ETN)/CPU13(-ETN)/CPU22/CPU23).

For details, refer to the SYSMAC CJ-series Operation Manual (Cat. No. W474) and the SYSMAC CJ-series Built-in I/O Operation Manual (Cat. No. W395).

### ■ CJ1M CPU Units (with Built-in I/O)

			Specifications										
Product name		I/O capacity/ Mountable Units (Expansion Racks)	Program capacity	Data memory capacity	LD instruc- tion execu- tion time	Built-in I/O	5 V	24 V	Model	Standards			
	Built-in I/O (See note 2.)	640 points/ 20 Units (1 Expansion Racks max.)	20K steps	32K words (DM: 32K words, EM: None)		10 inputs and	0.64 (See note 1.)		CJ1M-CPU23 (See note 3.)				
CJ1M CPU Units		320 points/ 10 Units (No Expansion Rack)	10K steps		(DM: 32K words, EM:	words, EM:	words, EM:	10K steps words, EM:	0.1 μs	6 outputs, 2 counter inputs, 2 pulse outputs	0.64 (See note 1.)		CJ1M-CPU22 (See note 3.)
		160 points/ 10 Units (No Expansion Rack)	5K steps			,	0.64 (See note 1.)		CJ1M-CPU21 (See notes 2 and 3.)				

- Note 1. Current consumptions include current for a Programming Console. Add 0.15 A per Adapter when using NT-AL001 RS-232C/RS-232A Adapters.

  Add 0.04 A per Adapter when using CJ1W-CIF11 RS-422A Adapters.
  - 2. The CJ1M low-end models (CJ1M-CPU11(-ETN)/CPU21) have different specifications for the overhead processing time, pulse start time, number of subroutines, number of jumps, number of scheduled interrupts, and number of PWM outputs than the other CJ1M models (CJ1M-CPU12(-ETN)/CPU13(-ETN)/CPU23(-ETN)/CPU23).
    - For details, refer to the SYSMAC CJ-series Operation Manual (Cat. No. W474) and the SYSMAC CJ-series Built-in I/O Operation Manual (Cat. No. W395).
  - 3. The connector for built-in I/O in the CJ1M-CPU21/22/23 is not included. Purchase one of the connectors or connector cables, refer to connectors or connector cables on page 40.

### **■ CJ1M CPU Units (with Ethernet function)**

	Specifications						Current consumption (A)			
Proc	duct name	I/O capacity/ Mountable Units (Expansion Racks)	Program capacity	Data memory capacity	LD instruc- tion execu- tion time	Ethernet function	5 V	24 V	Model	Standards
	Ethernet function	640 points/ 20 Units (1 Expansion Racks max.)	20K steps	32K words (DM: 32K words, EM: None) 0.1 μs	(DM: 32K words, EM: 0.1 μs		0.95 (See note 2.)		CJ1M-CPU13-ETN	
CJ1M CPU Units		320 points/ 10 Units (No Expansion Rack)	10K steps			YES (See note 1.)	0.95 (See note 2.)		CJ1M-CPU12-ETN	UC1, N, L, CE
		160 points/ 10 Units (No Expansion Rack)	5K steps				0.95 (See note 2.)		CJ1M-CPU11-ETN (See notes 3.)	

Note 1. Ethernet function

The Ethernet functional element provides the main functions of the CJ1W-ETN21 Ethernet Unit.

Physical layer	Maximum number of nodes in FINS network	Communications service
100BASE-TX, 10BASE-T	254	FINS communications service FTP server Automatically adjusted clock information. Web functions

Socket services and sending/receiving mail are not supported.

- Current consumptions include current for a Programming Console. Add 0.15 A per Adapter when using NT-AL001 RS-232C/RS-232A Adapters.
   Add 0.04 A per Adapter when using CJ1W-CIF11 RS-422A Adapters.
- 3. The CJ1M low-end models (CJ1M-CPU11(-ETN)/CPU21) have different specifications for the overhead processing time, number of subroutines, number of jumps, and number of scheduled interrupts than the other CJ1M models (CJ1M-CPU12(-ETN)/CPU13(-ETN)/CPU22/CPU23). For details, refer to the SYSMAC CJ-series Operation Manual (Cat. No. W474).

### **■** CJ1G Loop-control CPU Units

Product name	Specif	Current cons	sumption (A)	Model	Standards	
Product name	CPU Unit	Loop Controller	5 V	24 V	Wodei	Standards
	Same as for CJ1G-CPU45H.	Number of function blocks: 300 blocks max.	1.06 (See note.)		CJ1G-CPU45P	UC1, CE
CJ1G Loop- control CPU Units					CJ1G-CPU45P-GTC	
	Same as for CJ1G-CPU44H.		1.06 (See note.)		CJ1G-CPU44P	
	Same as for CJ1G-CPU43H.		1.06 (See note.)		CJ1G-CPU43P	,
	Same as for CJ1G-CPU42H.	Number of function blocks: 50 blocks max.	1.06 (See note.)		CJ1G-CPU42P	

Note: Current consumptions include current for a Programming Console. Add 0.15 A per Adapter when using NT-AL001 RS-232C/RS-232A Adapters. Add 0.04 A per Adapter when using CJ1W-CIF11 RS-422A Adapters.

### ● Connector Cables for Built-in I/O in CJ1M-CPU2□ CPU Units

The connector for built-in I/O in the CJ1M-CPU21/22/23 is not included.

Purchase one of the connectors or connector cables in the following table separately.

Product name			Specifications		Model	Standards
Applicable Connector						
	MIL Flat Cable Co	onnectors (Pressure-fitted Connector	XG4M-4030-T			
		Slim type (M3 scr	rew terminals, 40-pin)			
Normal Connection Method for Built-in I/O (When Connector-Terminal Block Conversion Unit is Used)		Similary (wis sciew terminals, 40-pm)			XW2D-40G6	
CJ1M-CPU2□ (with Built-in I/O)  Built-in I/O Connector	Connector-Ter- minal Block Conversion Units	Through type (M3	3 screw terminals, 40-pin)		XW2B-40G4	
Special Connecting Cable XW2Z		Through type (M3	3.5 screw terminals, 40-pin)		XW2B-40G5	
Conversion Unit XW2□-40G□	Connecting			Cable length: 1 m	XW2Z-100K	
	Cable for			Cable length: 1.5 m	XW2Z-150K	
Terminal Block	Connector-			Cable length: 2 m	XW2Z-200K	-
	Terminal Block				XW2Z-300K	-
	Conversion Units			Cable length: 3 m		-
		<u> </u>		Cable length: 5 m	XW2Z-500K	
	Servo	For 1 axis			XW2B-20J6-8A	
	Relay Units	For 2 axes			XW2B-40J6-9A	
	Connecting Cable for Servo Relay Units		Cable for CJ1M CPU Unit	Cable length: 0.5 m	XW2Z-050J-A33	1
		OMNUC G5/G Series		Cable length: 1 m	XW2Z-100J-A33	
			Servo Driver Connecting Cables	Cable length: 1 m	XW2Z-100J-B31	
Connection to Servo Driver with Built-in I/O  CJ1M-CPU2 (with Built-in I/O)				Cable length: 2 m	XW2Z-200J-B31	-
Built-in I/O Connector  Connecting Cables for CJ1M CPU Units  • For OMNUC G5/G Series:			Cable for CJ1M CPU Unit	Cable length: 0.5 m	XW2Z-050J-A33	-
XW2Z-□□□J-A33 • For SMARTSTEP2: XW2Z-□□□J-A33		SMARTSTEP2	Servo Driver Connecting Cables	Cable length: 1 m	XW2Z-100J-A33	-
Servo Relay Unit for 1 axis XW2B-20J6-8A				Cable length: 1 m	XW2Z-100J-B32	
Servo Driver Connecting Cables  • For OMNUC G5/G Series:  XW2Z-□□□J-B31				Cable length: 2 m	XW2Z-200J-B32	
For SMARTSTEP2:     XW2ZJ-B32     Servo Driver     OMNUC G5 Series     R88D-KT		OMADIOTES	Cable for CJ1M CPU Unit	Cable length: 1 m	XW2Z-100J-A26	
• OMNUC G Series R88D-GT     • SMARTSTEP2: R7D-BP  When two axes are used, two Connecting Cables are required at the Servo Driver for each Servo Relay Unit.		Cable for Servo Junior	Servo Driver Connecting Cables	Cable length: 1 m	XW2Z-100J-B17	
		SMARTSTEP A	Cable for CJ1M CPU Unit	Cable length: 1 m	XW2Z-100J-A26	
		Series	Servo Driver Connecting Cables	Cable length: 1 m	XW2Z-100J-B5	
				Cable length: 2 m	XW2Z-200J-B5	
			Cable for CJ1M CPU Unit	Cable length: 0.5 m	XW2Z-050J-A27	-
		OMNUC W		Cable length: 1 m	XW2Z-100J-A27	· 
		OMNUC W Series	Servo Driver Connecting Cables	Cable length: 1 m	XW2Z-100J-B4	1
				Cable length: 1 m	AVV2Z-1000-D4	

### **■** Power Supply Units

One Power Supply Unit is required for each Rack.

			0	utput capac	ity	Options				
Prod	luct name	Power supply voltage	5-VDC output capacity	24-VDC output capacity	Total power consump-tion	24-VDC service power supply	RUN output	Maintenance forecast monitor	Model	Standards
		5 A	0.8 A 25 W	or w	No	Yes	CJ1W-PA205C			
AC Power Supply Unit	100 to 240	23 W		Yes	No	CJ1W-PA205R	UC1, N, L,			
	a aguas		2.8 A	0.4 A	14 W	No	No	No	CJ1W-PA202	CE
DC Power		- 24 VDC	5A	0.8 A	25 W		No	No	CJ1W-PD025	
Supply Unit	CERCOLIE MANAGEMENT OF THE PROPERTY OF THE PRO	24 400	2 A	0.4 A	19.6 W	_	No	No	CJ1W-PD022	UC1, CE

### **Expansion Racks**

Select the I/O Control Unit, I/O Interface Unit, Expansion Connecting Cable, and CJ-series Power Supply Unit.

### ■ CJ-series I/O Control Unit (Mounted on CPU Rack when Connecting Expansion Racks)

Product name	name Specifications		rent nption A)	Model	Standards
		5 V	24 V		
CJ-series I/O Control Unit	Mount one I/O Control Unit on the CJ-series CPU Rack when connecting one or more CJ-series Expansion Racks.  Connecting Cable: CS1W-CN□□3 Expansion Connecting Cable  Connected Unit: CJ1W-II101 I/O Interface Unit  Mount to the right of the CPU Unit.	0.02		CJ1W-IC101	UC1, N, L, CE

 $\textbf{Note:} \ \ \text{Mounting the I/O Control Unit in any other location may cause faulty operation.}$ 

### ■ CJ-series I/O Interface Unit (Mounted on Expansion Rack)

Product Name	Specifications		rent mption A)	Model	Standards
		5 V	24 V		
CJ-series I/O Interface Unit	One I/O Interface Unit is required on each Expansion Rack. Connecting Cable: CS1W-CN□□3 Expansion Connecting Cable Mount to the right of the Power Supply Unit.	0.13		CJ1W-II101	UC1, N, L, CE

 $\textbf{Note:} \ \ \textbf{Mounting the I/O Interface Unit in any other location may cause faulty operation}.$ 

### ■ I/O Connecting Cables

Product name	Specifications	Model	Standards	
		Cable length: 0.3 m	CS1W-CN313	
I/O Connecting		Cable length: 0.7 m	CS1W-CN713	
Cable	Connects an I/O Control Unit on CJ-series CPU Rack to an I/O Interface Unit on a CJ-series Expansion Rack. or     Connects an I/O Interface Unit on CJ-series Expansion Rack to an I/O Interface Unit on another CJ-series Expansion Rack.	Cable length: 2 m	CS1W-CN223	N, L, CE
or • Conne		Cable length: 3 m	CS1W-CN323	
		Cable length: 5 m	CS1W-CN523	
		Cable length: 10 m	CS1W-CN133	
			CS1W-CN133-B2	

### **Programming Devices**

### **■** Support Software

Product name	Specifications	Number of licenses	Media	Model	Standards
	CX-One runs on the following OS. Windows XP (Service Pack 3 or higher), Vista, or 7 Note: Except for Windows XP 64-bit version.  CX-One Version 4. includes CX-Programmer Ver.9. and CX-Simulator Ver. 1. includes CX-Programmer Ver.9.	1 license		CXONE-AL01D-V4	
FA Integrated Tool Package CX-One Ver. 4.□		3 licenses	DVD	CXONE-AL03D-V4	
		10 licenses		CXONE-AL10D-V4	
		30 licenses		CXONE-AL30D-V4	
		50 licenses		CXONE-AL50D-V4	

Note: The CX-One is also available on CD (CXONE-AL□□C-V4).

Site licenses are available for users who will run CX-One on multiple computers. Ask your OMRON sales representative for details.

### Support Software in CX-One Version 4. $\square$

The following tables lists the Support Software that can be installed from CX-One

Support Software in CX-One	Outline
CX-Programmer Ver.9.□	Application software to create and debug programs for SYSMAC CS/CJ/CP/NSJ-series, C-series, and CVM1/C-series CPU Units. Data can be created and monitored for high-speed-type Position Control Units and Position Control Units with EtherCAT interface.
CX-Integrator Ver.2.□	Application software to build and set up FA networks, such as Controller Link, DeviceNet, CompoNet, CompoWay, and Ethernet networks. The Routing Table Component and Data Link Component can be started from here. DeviceNet Configuration functionality is also included.
Switch Box Utility Ver.1.□	Utility software that helps you to debug PLCs. It helps you to monitor the I/O status and to monitor/change present values within the PLC you specify.
CX-Protocol Ver.1.□	Application software to create protocols (communications sequences) between SYSMAC CS/CJ/CP/NSJ-series or C200HX/HG/HE Serial Communications Boards/Units and general-purpose external devices.
CX-Simulator Ver.1.□	Application software to simulate SYSMAC CS/CJ/CP/NSJ-series CPU Unit operation on the computer to debug PLC programs without a CPU Unit.
CX-Position Ver.2.□	Application software to create and monitor data for SYSMAC CS/CJ-series Position Control Units (except for high-speed type).
CX-Motion-NCF Ver.1.□	Application software to create and monitor data for SYSMAC CS/CJ-series Position Control Units with MECHATROLINK-II interface (MC□71).
CX-Motion-MCH Ver.2.□	Application software to create data and motion programs and to monitor data for SYSMAC CS/CJ-series Mosion Control Units with MECHATROLINK-II interface (MCH71).
CX-Motion Ver.2.□	Application software to create data for SYSMAC CS/CJ-series, C200HX/HG/HE, and CVM1/CV-series Motion Control Units, and to create and monitor motion control programs.
CX-Drive Ver.2.□	Application software to set and control data for Inverters and Servos.
CX-Process Tool Ver.5.□	Application software to create and debug function block programs for SYSMAC CS/CJ-series Loop Controllers (Loop Control Units/Boards, Process Control CPU Units, and Loop Control CPU Units).
Faceplate Auto-Builder for NS Ver.3.□	Application software that automatically outputs screen data as project files for Ns-series PTs from tag information in function block programs created with the CX-Process Tool.
CX-Designer Ver.3.□	Application software to create screen data for NS-series PTs.
NV-Designer Ver.1.□	Application software to create screen data for NV-series small PTs.
CX-Configurator FDT Ver.1.□	Application software for setting various units by installing its DTM module.
CX-Thermo Ver.4.□	Application software to set and control parameters in components such as Temperature Control Units.
CX-FLnet Ver.1.□	Application software for system setting and monitoring of SYSMAC CS/CJ-series FI-net Units.
Network Configurator Ver.3.□	Application software to set up tag data links for CJ2 (Built-in EtherNet/IP) CPU Units and EtherNet/IP Units.
CX-Server Ver.4.□	Middleware necessary for CX-One applications to communicate with OMRON components, such as PLCs, Display Devices, and Temperature Control Units.
PLC Tools (Installed automatically.)	A group of components used with CX-One applications, such as the CX-Programmer and CX-Integrator. Includes the following: I/O tables, PLC memory, PLC Setup, Data Tracing/Time Chart Monitoring, PLC Error Logs, File Memory, PLC clock, Routing Tables, and Data Link Tables.

Note: Approx. 2.8 GB or more available space is required to install the complete CX-One package.

## ■ Cables for Connecting to Support Software in the CX-One (e.g., the CX-Programmer)

			Specifications					
Produc	t Name	Applicable computers	Connection configuration		Cable length	Remarks	Model	Standards
			IBM PC/AT or compatible computer + CS1W-626 + CPU Unit peripheral port  RS-232C  Peripheral port		2 m	Used for	CS1W-CN226	
Program- ming Device		Connects IBM	IBM PC/AT or Connecting Cables for peripheral port (RS-232C, 9-pin)		6 m	Peripheral Bus or Host Link.	CS1W-CN626	CE
Connecting Cables for Peripheral Port		PC/AT or compatible computers, D-Sub 9-pin	The following connection method can be use connecting to an IBM PC/AT or compatible con RS-232C cable: IBM PC/AT or compatible computer + XW2Z-2 or XW2Z-500S-CV/V + CS1W-CN118 + CPU peripheral port  WW2Z-500S-CV/V XW2Z-500S-CV/V RS-232C Cables  CS1W-CN118	0.1 m	Used for connecting XW2Z-200S- CV/V or XW2Z- 500S-CV/V RS- 232C Cable to the peripheral port.	CS1W-CN118	CE	
			IBM PC/AT or compatible computer + XW2Z-2 or XW2Z-500S-CV/V + RS-232C port of CPU		2 m	Used for Peripheral Bus	XW2Z-200S-CV	
Programmi Device Cor Cables for Port	necting	Connects IBM PC/AT or compatible computers, D-Sub 9-pin	Serial Communications Board or Unit	) Onlt or	5 m	or Host Link. Anti-static connectors	XW2Z-500S-CV	
			compatible computer XW2Z-500S-CV/V (5m) CPU Unit built-in		2 m	Used for Host Link only.	XW2Z-200S-V	
			(RS-232C, 9-pin) RS-232C Cables RS-232C port			Peripheral Bus not supported.	XW2Z-500S-V	
USB-Serial	Commen		IBM PC/AT or compatible computer + CS1W-CIF31 + CS1W-CN226/626 + CPU Unit peripheral port CS1W-CIF31 USB-Serial Conversion Cable e.g., CS1W-CN226/626 e.g., CS1W-CN226/626 XW2Z-200S-CV/500S-CV, XW2Z-200S-CV/500S-CV, XW2Z-200S-V, CQM1-CIF02	Connect USB Serial Conver- sion Cable to		Used for Peripheral Bus or Host Link.		
sion Cable driver (on a disk)	and PC	IBM PC/AT or compatible	IBM PC/AT or compatible computer + CS1W-CIF31 + XW2Z-200S-CV/500S-CV + CS1W-CN118 + CPU Unit peripheral port	Serial Connect- ing	0.5 m	Used for Peripheral Bus or Host Link.	CS1W-CIF31	N
Complies v Specification		computer (USB port)	IBM PC/AT or compatible computer + CS1W-CIF31 + XW2Z-200S-V/500S + CS1W-CN118 + CPU Unit peripheral port	Cable, and con- nect to the PLC	U.5 III	Used for Host Link only. Peripheral Bus not supported.	33111 011 011	
			IBM PC/AT or compatible computer + CS1W-CIF31 + XW2Z-200S-CV/500S-CV + RS-232C port of CPU Unit or Serial Communications Unit	periph- eral port or RS- 232C port.		Used for Peripheral Bus or Host Link.		
			IBM PC/AT or compatible computer + CS1W-CIF31 + XW2Z-200S-V/500S-V + RS-232C port of CPU Unit or Serial Communications Unit			Used for Host Link only. Peripheral Bus not supported.		

#### <Note>

There are two serial communications modes for connecting Support Software in the CX-One (e.g., the CX-Programmer) to the CJ Series.

Serial communications mode	Features
Peripheral Bus	High-speed communications are enabled in the Peripheral Bus Mode, so normally connect with this serial communications mode when using Support Software in the CX-One, such as the CX-Programmer  • Supported for 1:1 connection only.  • The baud rate at the Support Software is automatically recognized when the connection is made.
Host Link (SYSWAY)	Host Link (SYSWAY) is generally the protocol for communications with a host computer. Either a 1:1 or 1:N connection can be used.  • Slower than the peripheral bus.  • Connections is possible via a modem or optical adapter, long-distance connection is possible using RS-422A/485, and 1:N connections are possible.

## **■** Programming Consoles

Product name	Specifications	Cable model (Purchased separately.)	Connection configuration	Model	Standards
	Connects to	Not required. (Cable is included.)	Standard accessory with CQM1H-PRO01. Peripheral port Console Keyboard CS1W-KS001 Console	CQM1H-PRO01-E	U, C, N, CE
Programming Consoles	peripheral port on CPU Unit only. (No connection is required at the RS- 232C port.) An English Keyboard Sheet (CS1W-KS001-E) is required.	CS1W-CN114: 0.05 m	Standard accessory with CQM1-PRO01 Peripheral port Console Keyboard CS1W-KS001 Console (0.05 m) Standard accessory with CQM1-PRO01 CQM1H-PRO01 CS1W-CN114 (0.05 m)	CQM1-PRO01-E	
		CS1W-CN224: 2 m CS1W-CN624: 6 m	Programming Console Keyboard CS1W-KS001  C200H-PRO27 Programming Console Meyboard CS1W-KS001	C200H-PRO27-E	
Programming Console Key Sheet	For CQM1H-PRO01	-E, CQM1-PRO01	CS1W-KS001-E		
Pro- gram-	Connects the CQM1	-PRO01-E Progra	mming Console. (Length: 0.05 m)	CS1W-CN114	
ming	Connects the C200	H-PRO27-E Progra	amming Console. (Length: 2 m)	CS1W-CN224	CE
Console Connecting Cables	Connects the C200l	H-PRO27-E Progra	amming Console. (Length: 6 m)	CS1W-CN624	

## **Optional Products and Maintenance Products**

Product name	Specifications	Model	Standards
Memory Cards	Flash memory, 128 MB	HMC-EF183	
	Memory Card Adapter (for computer PCMCIA slot)	HMC-AP001	CE

Product name	Sp	ecifications	Model	Standards
Battery Set	Battery for CJ1G/H-CPU□□H-R/H/P CPU Unit maintenance	Note 1.The battery is included as a standard accessory with the CPU Unit. 2. The battery service life is 5 years at 25°C.	CPM2A-BAT01	
	Battery for CJ1M-CPU□CPU Unit maintenance	(The service life depends on the ambient operating temperature and the power conditions.)  3. Use batteries within two years of manufacture.	CJ1W-BAT01	
End Cover	Mounted to the right-hand side of CJ-series CPU Racks or Expansion Racks.	One End Cover is provided as a standard accessory with each CPU Unit and I/O Interface Unit.	CJ1W-TER01	UC1, N, L,
RS-422A Adapter	Converts RS-233C to RS-422A/RS-485. (Application example: With a CJ1M CPU Uni RS-232C port of the CPU Unit.)	t, the Adapter is used for Serial PLC Link at the built-in	CJ1W-CIF11	UC1, N, L, CE

Product name	Specifications	Model	Standards	
Product name	Connection configuration	Cable length	Wodel	Statiuatus
NS-series PT Connect-	Cable for connecting between an NS-series PT and the RS-232C port on the CPU Unit or Serial Communications Board  NS-series PT	2 m	XW2Z-200T	
ing Cables	XW2Z-200T (2 m)	5 m	XW2Z-500T	
_	Cable for connecting between an NS-series PT and the peripheral port on	2 m	XW2Z-200T-2	
	the CPU Unit	5 m	XW2Z-500T-2	

## **DIN Track Accessories**

Product name	Specifications	Model	Standards
DIN Track	Length: 0.5 m; Height: 7.3 mm	PFP-50N	
	Length: 1 m; Height: 7.3 mm	PFP-100N	
	Length: 1 m; Height: 16 mm	PFP-100N2	
End Plate	There are 2 stoppers provided with CPU Units and I/O Interface Units as standard accessories to secure the Units on the DIN Track.	PFP-M	

## **Basic I/O Units**

## **■ Input Units**

Unit clas-	Product			Specifications			Currer	nt con- ion (A)		
sification	name	I/O points	Input voltage and current	Commons	External connection	No. of words allocated	5 V	24 V	Model	Standards
		8 inputs	12 to 24 VDC, 10 mA	Independent contacts	Removable terminal block	1 word	0.08		CJ1W-ID201	
	DC Input Units	16 inputs	24 VDC, 7 mA	16 points, 1 common	Removable terminal block	1 word	0.08		CJ1W-ID211	
	Date:	16 inputs High-speed type	24 VDC, 7 mA	16 points, 1 common	Removable terminal block	1 word	0.13		CJ1W-ID212	
		32 inputs	24 VDC, 4.1 mA	16 points, 1 common	Fujitsu connector	2 words	0.09		CJ1W-ID231 (See note.)	
CJ1 Basic		32 inputs	24 VDC, 4.1 mA	16 points, 1 common	MIL connector	2 words	0.09		CJ1W-ID232 (See note.)	UC1, N, L,
I/O Units		32 inputs High-speed type	24 VDC, 4.1 mA	16 points, 1 common	MIL connector	2 words	0.20		CJ1W-ID233 (See note.)	CE CE
	16: S	64 inputs	24 VDC, 4.1 mA	16 points, 1 common	Fujitsu connector	4 words	0.09		CJ1W-ID261 (See note.)	
		64 inputs	24 VDC, 4.1 mA	16 points, 1 common	MIL connector	4 words	0.09		CJ1W-ID262 (See note.)	
	AC Input Units	8 inputs	200 to 24 VAC, 10 mA (200 V, 50 Hz)	8 points, 1 common	Removable Terminal Block	1 words	0.08		CJ1W-IA201	
		16 inputs	100 to 120 VAC, 7 mA (100 V, 50 Hz)	16 points, 1 common	Removable Terminal Block	1 words	0.09		CJ1W-IA111	

Note: Connectors are not provided with these connector models. Either purchase one of the following 40-pin Connectors, or use an OMRON XW2 Connector-Terminal Block Conversion Unit or a G7 I/O Relay Terminal.

## **■** Output Units

Unit clas-	Product			Specifications			No. of words	consu	rent mption A)	Model	Standards			
sification	name	Output type	I/O points	Maximum switching capacity	Commons	External connection	allocated	5 V	24 V					
	Relay Contact Output Units		8 outputs	250 VAC/24 VDC, 2 A	Independent contacts	Removable terminal block	1 words	0.09	0.048 max.	CJ1W-OC201				
	A CONTRACTOR OF THE PARTY OF TH		16 outputs	250 VAC/24 VDC, 2 A	16 points, 1 common	Removable terminal block	1 words	0.11	0.096 max.	CJ1W-OC211				
	Triac Output Unit		8 outputs	250 VAC, 0.6 A	8 points, 1 common	Removable terminal block	1 words	0.22		CJ1W-OA201				
			8 outputs	12 to 24 VDC, 2 A	4 points, 1 common	Removable terminal block	1 words	0.09		CJ1W-OD201				
	Transis- tor Output Units					8 outputs	12 to 24 VDC, 0.5 A	8 points, 1 common	Removable terminal block	1 words	0.10		CJ1W-OD203	
			16 outputs	12 to 24 VDC, 0.5 A	16 points, 1 common	Removable terminal block	1 words	0.10		CJ1W-OD211				
CJ1 Basic I/O Units		Sinking	16 outputs High-speed type	24 VDC, 0.5 A	16 points, 1 common	Removable terminal block	1 words	0.15		CJ1W-OD213	UC1, N, L, CE			
Onits			32 outputs	12 to 24 VDC, 0.5 A	16 points, 1 common	Fujitsu connector	2 words	0.14		CJ1W-OD231 (See note.)				
	1110		32 outputs	12 to 24 VDC, 0.5 A	16 points, 1 common	MIL connector	2 words	0.14		CJ1W-OD233 (See note.)				
			32 outputs High-speed type	24 VDC, 0.5 A	16 points, 1 common	MIL connector	2 words	0.22		CJ1W-OD234 (See note.)				
			64 outputs	12 to 24 VDC, 0.3 A	16 points, 1 common	Fujitsu connector	4 words	0.17		CJ1W-OD261 (See note.)				
			64 outputs	12 to 24 VDC, 0.3 A	16 points, 1 common	MIL connector	4 words	0.17		CJ1W-OD263 (See note.)				
			8 outputs	24 VDC, 2 A Short-circuit protection	4 points, 1 common	Removable terminal block	1 words	0.11		CJ1W-OD202				
			8 outputs	24 VDC, 0.5 A Short-circuit protection	8 points, 1 common	Removable terminal block	1 words	0.10		CJ1W-OD204				
		Sourcing	16 outputs	24 VDC, 0.5 A Short-circuit protection	16 points, 1 common	Removable terminal block	1 words	0.10		CJ1W-OD212				
			32outputs	24 VDC, 0.5 A Short-circuit protection	16 points, 1 common	MIL connector	2 words	0.15		CJ1W-OD232 (See note.)				
			64 outputs	12 to 24 VDC, 0.3 A	16 points, 1 common	MIL connector	4 words	0.17		CJ1W-OD262 (See note.)				

Note: Connectors are not provided with these connector models. Either purchase one of the following 40-pin Connectors, or use an OMRON XW2 Connector-Terminal Block Conversion Unit or a G7 I/O Relay Terminal.

#### ■ I/O Units

Unit				Specifica	tions			Current consumption (A)				
classifica- tion	Product name	Output	I/O points	Input voltage, Input current	Commons	External	No. of words	5 V	24 V	Model	Standards	
		type	i/o points	Maximum switching capacity		connection	allocated		27 7			
		Sinking	16 inputs	24 VDC, 7 mA	16 points, 1 common	Fujitsu	2 words	0.13		CJ1W-MD231	UC1, N,	
		Sirikiriy	16 outputs	250 VAC/24 VDC, 0.5 A	16 points, 1 common	connector	2 Words	0.13		(See note 2.)	CE	
	DC Input/ Transis-	Sinking	16 inputs	24 VDC, 7 mA	16 points, 1 common	MIL	2 words	0.13		CJ1W-MD233		
	tor Output Units		Silikiliy	16 outputs	12 to 24 VDC, 0.5 A	16 points, 1 common	connector	or 2 words	0.10		(See note 2.)	
		Sinking	32 inputs	24 VDC, 4.1 mA	16 points, 1 common	Fujitsu	1 4 Words	0.14		CJ1W-MD261 (See note 1.)	UC1, N,	
0.14		Silikiliy	32 outputs	12 to 24 VDC, 0.3 A	16 points, 1 common	connector		0.14				
CJ1 Basic I/O		Sinking	32 inputs	24 VDC, 4.1 mA	16 points, 1 common	MIL	4 words	0.14		CJ1W-MD263 (See note 1.)		
Units	26. 88	Siriking	32 outputs	12 to 24 VDC, 0.3 A	16 points, 1 common	connector	4 words	0.14				
		Sourcing	16 inputs	24 VDC, 7 mA	16 points, 1 common	MIL	2 words	0.13		CJ1W-MD232	UC1, N, L,	
		Sourcing	16 outputs	24 VDC, 0.5 A Short-circuit protection	16 points, 1 common	connector	2 Words	0.13		(See note 2.)	CE	
	TTL I/O Units		32 inputs	5 VDC, 35 mA	16 points, 1 common	MIL	4 morele	0.19		CJ1W-MD563	UC1, N,	
			32 outputs	5 VDC, 35 mA	16 points, 1 common	connector	4 words	0.19		(See note 1.)	CE	

#### ● Applicable Connectors

## Fujitsu Connectors for 32-input, 32-output, 64-input, 64-output, 32-input/32-output, and 16-input/16-output Units

Name	Connection	Part name	Applicable Units	Model	Standards
40-pin Connectors	Soldered	FCN-361J040-AU Connector FCN-360C040-J2 Connector Cover	Fujitsu Connectors: CJ1W-ID231(32 inputs): 1 per Unit CJ1W-ID261 (64 inputs) 2 per Unit	C500-CE404	
	FCN-36	FCN-363J040 Housing FCN-363J-AU Contactor FCN-360C040-J2 Connector Cover	CJ1W-OD231 (32 outputs):1 per Unit CJ1W-OD261 (64 outputs): 2 per Unit CJ1W-MD261 (32 inputs, 32 outputs): 2 per Unit	C500-CE405	
	Pressure welded	FCN-367J040-AU/F		C500-CE403	
24-pin Connectors	Soldered	FCN-361J024-AU Connector FCN-360C024-J2 Connector Cover	Fujitsu Connectors: CJ1W-MD231 (16 inputs, 16 outputs): 2 per Unit	C500-CE241	
	Crimped	FCN-363J024 Housing FCN-363J-AU Contactor FCN-360C024-J2 Connector Cover		C500-CE242	
	Pressure welded	FCN-367J024-AU/F		C500-CE243	

Note 1 .Connectors are not provided with these connector models. Either purchase one of the following 40-pin Connectors, or use an OMRON XW2□ Connector-Terminal Block Conversion Unit or a G7□ I/O Relay Terminal.
 2. Connectors are not provided with these connector models. Either purchase one of the following 20-pin or 24-pin Connectors, or use an OMRON XW2□ Connector-Terminal Block Conversion Unit or a G7□ I/O Relay Terminal.

MIL Connectors for 32-input, 32-output, 64-input, 64-output, 32-input/32-output, and 16-input/16-output Units

Name	Connection	Part name	Applicable Units	Model	Standards
40-pin Connectors	Pressure welded	FRC5-AO40-3TOS	MIL Connectors: CJ1W-ID232 (32 inputs): 1 per Unit CJ1W-OD232/233 (32 outputs):1 per Unit CJ1W-ID262 (64 inputs): 2 per Unit CJ1W-OD262/263 (64 outputs): 2 per Unit CJ1W-MD263/563 (32 inputs, 32 outputs): 2 per Unit	XG4M-4030-T	
20-pin Connectors	Pressure welded	FRC5-AO20-3TOS	MIL Connectors: CJ1W-MD232/233 (16 inputs, 16 outputs): 2 per Unit	XG4M-2030-T	

## ■ Interrupt Input Units

Unit clas-	Product			Sį	pecifications			No. of	Currer			
sification		I/O points	Input voltage current	Commons	Input pulse width conditions	Max. Units mountable per Unit	1	words allocated	5 V	24 V	Model	Standards
CJ1 Basic I/O Units	Interrupt Input Unit	16 inputs	24 VDC, 7 mA	16 points, 1 common	ON time: 0.05 ms max. OFF time: 0.5 ms max.	2	Remov- able termi- nal block	1 word	0.08		CJ1W-INT01	UC1, N, L, CE

### ■ Quick-response Input Units

				Speci	fications		No. of		nt con- ion (A)		
		I/O points	Input voltage, Input current	Commons	Input pulse width conditions	External connection	words allocated	5 V	24 V	Model	Standards
CJ1 Basic I/O Units	High- speed Input Unit	16 inputs	24 VDC, 7 mA	16 points, 1 common	ON time: 0.05 ms max. OFF time: 0.5 ms max.	Removable terminal block	1 word	0.08		CJ1W-IDP01	UC1, N, L, CE

Note: There are no restrictions on the mounting position or number of Units.

#### **■** B7A Interface Units

Unit clas-	Product		Specifica	itions		No. of words	Currer	nt con- ion (A)	Model	Standards
sification	name	I/O points	Send delay time	Output status when error occurs	External connection	allocated	5 V	24 V	Wodel	Standards
CJ1 Basic I/O	B7A Inter- face Units	64 inputs	Switchable between the	Hold			0.07		CJ1W-B7A14	
		64 outputs	following: Standard: 19.2 ms typ.		Removable terminal block	4 words	0.07		CJ1W-B7A04	UC1, CE
Units		32 inputs/ outputs	High-speed: 3 ms typ.	Hold (inputs only)			0.07		CJ1W-B7A22	

Note 1. Can be used only on CPU Racks, and not on Expansion Racks.

2. The locations where the Units can be mounted depend on the CPU Rack and the CPU Unit model.

CJ2H: From the slot next to the CPU Unit until the four slot.

CJ1G, CJ1H: From the slot next to the CPU Unit until the fifth slot.

CJ1M: From the slot next to the CPU Unit until the third slot.

## Special I/O Units and CPU Bus Units

#### ■ Process I/O Units

#### ● Isolated-type Units with Universal Inputs

			Signal		Conversion	Accuracy	External	No. of unit	Currer sumpt			
Unit classification	Product name	Input points	range selection	Signal range	speed	(at ambient tem- perature of 25°C)	connec-	num- bers allo- cated	5 V	24 V	Model	Standards
CJ1 Special I/O	Process Input Units (Isolated- type Units with Uni- versal	4 inputs	Set sepa- rately for each input	Universal inputs: Pt100 (3-wire), JPt100 (3-wire), Pt1000 (3-wire), Pt1000 (4-wire), Ft100 (4-wire), K, J, T, E, L, U, N, R, S, B, WRe5-26, PL II, 4 to 20 mA, 1 to 5 V, 0 to 1.25 V, 0 to 5 V, 0 to 10 V, ±100 mV selectable range -1.25 to 1.25 V, -5 to 5 V, -10 to 10 V, ±10 V selectable range, potentiometer	Resolution (conversion speed): 1/256,000 (conversion cycle: 60 ms/ 4 inputs) 1/64,000 (conversion cycle: 10 ms/ 4 inputs) 1/16,000 (conversion cycle: 5 ms/ 4 inputs)	Standard accuracy: ±0.05% of F.S.	Remov- able ter-	1	0.30		CJ1W-PH41U (See note 1.)	UC1, CE
Units	with Uni- ecial versal Inputs)	4 inputs	Set sepa- rately for each input	Universal inputs: Pt100, JPt100, Pt1000, K, J, T, L, R, S, B, 4 to 20 mA, 0 to 20 mA, 1 to 5 V, 0 to 5 V, 0 to 10 V	Conversion speed: 250 ms/ 4 inputs	Accuracy: Platinum resistance thermometer input: (±0.3% of PV or ±0.8°C, whichever is larger) ±1 digit max. Thermocouple input: (±0.3% of PV or ±1.5°C, whichever is larger) ±1 digit max. (See note 2.) Voltage or current input: ±0.3% of F.S. ±1 digit max.	block		0.32		CJ1W-AD04U	UC1, L, CE

Note 1. When using the CJ1W-PH41U, do not mount a Relay Output Unit in the same CPU Rack or Expansion Rack.

2. L and -100°C or less for K and T are ±2°C±1 digit max., and 200°C or less for R and S is ±3°C±1 digit max. No accuracy is specified for 400°C or less for B.

#### • Isolated-type Thermocouple Input Units

Unit clas-		Input	Signal range	Signal range	Conversion speed	(at ambient	External	No of linit		nt con- ion (A)		Standards
sification	name	points	selection		(resolution)	temperature of 25°C)	connection	allocated	5 V	24 V		
CJ1 Special	Process Input Units (Isolated- type Ther- mocouple Input	2 inputs	Set sep- arately for each input	Thermocouple: B, E, J, K, L, N, R, S, T, U, WRe5-26, PLII DC voltage: ±100 mV	Conversion speed: 10 ms/ 2 inputs, Resolution: 1/64,000	Standard accuracy: ±0.05% of F.S. (See note 1.)	Removable		0.18	0.06 (See note 2.)	CJ1W- PTS15	1101 05
I/O Units	Units)	4 inputs		Thermocouple: R, S, K, J, T, L, B	Conversion speed: 250 ms/ 4 inputs	Accuracy: (±0.3% of PV or ±1°C, whichever is larger) ±1 digit max. (See note 3.)	terminal block	1	0.25		CJ1W- PTS51	UC1, CE

Note 1. The accuracy depends on the sensors used and the measurement temperatures. For details, refer to the user's manual.

<sup>2.</sup> This is for an external power supply, and not for internal current consumption.

<sup>3.</sup> L and -100°C or less for K and T are ±2°C±1 digit max., and 200°C or less for R and S is ±3°C±1 digit max. No accuracy is specified for 400°C or less for B.

#### ● Isolated-type Resistance Thermometer Input Units

			Signal		Conversion	Accuracy	External	No. of unit		nt con- ion (A)		
Unit classification		Input points	range	Signal range	speed (resolution)	(at ambient temperature of 25°C)	connec- tion	num- bers allo- cated	5 V	24 V	Model	Standards
CJ1	Process Analog Input Units (Isolated- type Resis-	2 inputs	Set sep- arately for each input	Resistance ther- mometer: Pt100, JPt100, Pt50, Ni508.4	Conversion speed: 10 ms/ 2 inputs, Resolution: 1/64,000	Accuracy: ±0.05% of F.S. or ±0.1°C, whichever is larger.	Remov- able termi- nal block		0.18	0.07 (See note.)	CJ1W-PTS16	
Special I/O Units	tance Thermometer Input Units)	4 inputs	Com- mon inputs	Resistance ther- mometer: Pt100, JPt100	Conversion speed: 250 ms/ 4 inputs	Accuracy: ±0.3°C of PV or ±0.8°C, which- ever is larger, ±1 digit max.		1	0.25		CJ1W-PTS52	UC1, CE

Note: This is for an external power supply, and not for internal current consumption.

#### ● Isolated-type DC Input Units

Unit clas-		Input	Signal range selection	Conversion speed	(at ambient	External connec-	unit	Currer sumpt	nt con- ion (A)	Model	Standards
sification	name	points	3 · · · 3 · · · · · · · · · · · · · · ·	(resolution)	temperature of 25°C)	tion	numbers allocated	5 V	24 V		
CJ1 Special I/O Units	Isolated- type DC Input Units	2 inputs	DC voltage: 0 to 1.25 V, -1.25 to 1.25 V, 0 to 5 V, 1 to 5 V, -5 to 5 V, 0 to 10 V, -10 to 10 V, ±10 V selectable range DC current: 0 to 20 mA, 4 to 20 mA	Conversion speed: 10 ms/ 2 inputs  Resolution: 1/64,000	Standard accuracy: ±0.05% of F.S.	Remov- able terminal block	1	0.18	0.09 (See note.)	CJ1W-PDC15	UC1, CE

Note: This is for an external power supply, and not for internal current consumption.

#### ■ Analog I/O Units

## Analog Input Units

Unit type	Product name	Input points	Signal range selection	Signal range	Resolution	Conversion period	temperature	External connection	numbers	consu	A) .	Model	Standards
							of 25°C)		allocated	5 V	24 V		
CJ1 Special	Analog Input Unit	4 inputs	Set separately for each	1 to 5 V (1/ 0 to 10 V (1- 5 to 5 V (1- 10 to 10 V and 4 to 20 mA	1/20,000), /20,000), (1/40,000),	20 μs/1 point, 25 μs/2 points, 30 μs/3 points, 35 μs/4 points The Direct conversion is provided.	Voltage: ±0.2% of F.S. Current: ±0.4% of F.S.	Removable terminal	1	0.52		CJ1W-AD042	UC1, CE
I/O Units	Analog Input Units	8 inputs	input	1 to 5 V, 0 to 5 V,	1/4,000 (Settable	1 ms/point	Voltage:	block				CJ1W-AD081-V1	
		4 inputs		0 to 10 V, -10 to 10 V, 4 to 20 mA	to 1/8,000) (See note 1.)	(250 µs/point can also be set.) (See note 1.)	±0.2% of F.S. Current: ±0.4% of F.S. (See note 2.)			0.42		CJ1W-AD041-V1	UC1, N, L, CE

Note 1. The resolution and conversion speed cannot be set independently. If the resolution is set to 1/4,000, then the conversion speed will be 1 ms/point.

**<sup>2.</sup>** At 23 ±2°C

#### Analog Output Units

Unit type	Product name	nointe	Signal range selection	Signal range	Resolution	Conversion period	temperature	External connection	External power supply	No. of unit numbers	consu	rrent mption A)	Model	Standards
			SCICOLIOII				of 25°C)		Supply	allocated	5 V	24 V		
	Analog Output Unit High-speed type	4 outputs		1 to 5 V (1/ 0 to 10 V (1/ and -10 to 10 V	1/20,000),	$\begin{array}{c} 20~\mu\text{s}/\\ 1~\text{point},\\ 25~\mu\text{s}/\\ 2~\text{points},\\ 30~\mu\text{s}/\\ 3~\text{points},\\ 35~\mu\text{s}/\\ 4~\text{points}\\ \text{The Direct}\\ \text{conversion}\\ \text{is provided}. \end{array}$	±0.3% of F.S.				0.40		CJ1W-DA042V	UC1, CE
CJ1 Special I/O Units		8 outputs	Set sep- arately for each	1 to 5 V, 0 to 5 V, 0 to 10 V, -10 to 10 V	1/4,000 (Settable to	1 ms/point (Settable to 250 µs/	±0.3% of	Removable terminal block	24 VDC +10% -15%, 140 mA max.	1	0.14	0.14 (See note 2.)	CJ1W-DA08V	UC1, N, L, CE
VO Units	Analog Output Units	8 outputs	output	4 to 20 mA	1/8,000) (See note 1.)	point) (See note 1.)	F.S.	DIOCK	24 VDC +10% -15%, 170 mA max.		0.14	0.17 (See note 2.)	CJ1W-DA08C	UC1, N, CE
		4 outputs		1 to 5 V, 0 to 5 V, 0 to 10 V,	1/4,000	1 ms/point	Voltage: ±0.3% of F.S.		24 VDC +10% -15%, 200 mA max.		0.12	0.2 (See note 2.)	CJ1W-DA041	UC1, N,
		2 outputs		-10 to 10 V, -10 to 10 V, 4 to 20 mA	174,000	i mə/point	Current: ±0.5% of F.S.		24 VDC +10% -15%, 140 mA max.		0.12	0.14 (See note 2.)	CJ1W-DA021	L, CE

Note 1. The resolution and conversion speed cannot be set independently. If the resolution is set to 1/4,000, the conversion speed will be 1 ms/point.

2. This is for an external power supply, and not for internal current consumption.

#### ● Analog I/O Units

Unit clas-		No. of points	Signal range selec-	Signal range	Resolu- tion (See	Conversion period (See note.)	Accuracy (at ambient temperature	External connection		cons	rent ump- ı (A)	Model	Standards
			tion		note.)	(occ note.)	of 25°C)	lion	anocatea	5 V	24 V		
CJ1 Special I/O Units	Analog I/O Units	4 inputs 2 outputs	Set sepa- rately for each input	1 to 5 V, 0 to 5 V, 0 to 10 V, -10 to 10 V, 4 to 20 mA	1/4,000 (Settable to 1/8,000)	1 ms/point (Settable to 500 µs/point max.)	Voltage input: ±0.2% of F.S. Current input: ±0.2% of F.S. Voltage output: ±0.3% of F.S. Current output: ±0.3% of F.S.	Remov- able termi- nal block	1	0.58		CJ1W-MAD42	UC1, N, L, CE

Note: The resolution and conversion speed cannot be set independently. If the resolution is set to 1/4,000, then the conversion speed will be 1 ms/point.

## ■ Temperature Control Units

Unit clas-	Product		Specifica	itions	No. of unit		nt con- ion (A)	Model	Standards
sification	name	No. of loops	Temperature sensor inputs	Control outputs	allocated	5 V	24 V	Wodel	Standards
		4 loops		Open collector NPN outputs (pulses)		0.25		CJ1W-TC001	
		4 loops		Open collector PNP outputs (pulses)		0.25		CJ1W-TC002	
		2 loops, heater burnout detection function	Thermocouple input (R, S, K, J, T, B, L)	Open collector NPN outputs (pulses)		0.25		CJ1W-TC003	
CJ1 Special	Temper- ature Control Units	2 loops, heater burnout detection function		Open collector PNP outputs (pulses)	2	0.25		CJ1W-TC004	UC1, N,
I/O Units		4 loops		Open collector NPN outputs (pulses)	2	0.25		CJ1W-TC101	L, CE
		4 loops	Platinum	Open collector PNP outputs (pulses)		0.25		CJ1W-TC102	
		2 loops, heater burnout detection function	resistance thermometer input (JPt100, Pt100)	Open collector NPN outputs (pulses)		0.25		CJ1W-TC103	
		2 loops, heater burnout detection function		Open collector PNP outputs (pulses)		0.25		CJ1W-TC104	

## **■** High-speed Counter Unit

Unit clas-	Product		Specifications		No. of	Currer	nt con- ion (A)		
sification		Countable channels	Encoder A and B inputs, pulse input Z signals	Max. counting rate	numbers	5 V	24 V	Model	Standards
CJ1 Special	High-speed Counter Unit		Input voltage: 5 VDC, 12 V, or 24 V (5 V and 12 V are each for one axis only.)	50 kHz	4	0.28		CJ1W-CT021	UC1, N, L,
Special I/O Units		2	RS-422 line driver	500 kHz	+	0.20		001W-01021	CE

# ■Position Control Units • Position Control Units (High-speed type)

Position Control Units	Unit classifi-	Product name		•••	ecifications		No. of unit	cons	rent ump- ı (A)	Model	Standards
Pulse Counter Function	cation			Control outp	ut interface		allocated	5 V	24 V		
Pulse Counter Function		Position Control	Pulse-train ope	en-collector outp	ut with	2 axes		0.27		CJ1W-NC214	
Pulse-frain line-driver output with		Units	Pulse Counter	Function		4 axes		0.31		CJ1W-NC414	UC1 CE
Connecting Servo Drives: OMNUC G Series R8B0-4T Connecting Servo Drives: OMNUC G G Series R8B0-4T Connecting Servo Drives: OMNUC G G Series R8B0-4T Connecting Servo Drives: OMNUC G G Series R8B0-4T Connecting Servo Drives:		High-speed type	Pulse-train line	e-driver output wi	th	2 axes	2	0.27		CJ1W-NC234	001, 02
OMNUC G 58 eries R8B0-4T			Pulse Counter	Function		4 axes		0.31		CJ1W-NC434	
Connecting Servo Drives: OMNUC Westers R88D-WT					OMNUC G Series R88D-GT		Cable lengt	Cable length: 1 m		XW2Z-100J-G13	
OMNUC W Series R8BD-WT   Connecting Servo Drives: SMARTSTEP R7D-AP   Connecting Servo Drives: OMNUC W Series R8BD-WT   Connecting Servo Drives: OMNUC W Series R8B							Cable length: 3 m			XW2Z-300J-G13	
CJ1   Open-collector output   Position Control Unit Cables   Position Cables   Pos							Cable lengt	h: 1 m		XW2Z-100J-G16	
Connecting Servo Drives: OMNUC G Series R8B0-GT OMNUC Series R8B0-TO OMNUC G SERIES						4	Cable lengt	h: 3 m		XW2Z-300J-G16	
A SMARTSTEP2 R7D-BP Connecting Servo Drives: OMNUC W Series R88D-WT Connecting Servo Drives: OMNUC W Series R88D-WT Connecting Servo Drives: OMNUC G Series R88D-WT Connecting					OMNUC G Series R88D-GT	laxis	Cable lengt	h: 1 m		XW2Z-100J-G14	
CJ1							Cable lengt	h: 3 m		XW2Z-300J-G14	
Open-collector output  Onnecting Servo Drives: OMNUC G Series R8BD-GT OMNUC G SERIES GRBD-GT Cable length: 1 m							Cable lengt	h: 1 m		XW2Z-100J-G15	
CJ1 Special WO Units Position Control Unit Cables  Position Control Unit Cables  Position Control Unit Cables  Position Control Unit Cables  Connecting Servo Drives: OMNUC W Series R88D-WT Connecting Servo Drives: OMNUC W Series R88D-WT Connecting Servo Drives: OMNUC W Series R88D-WT Connecting Servo Drives: OMNUC G Series R88D-GT OMNUC G Series R88D-GT OMNUC G Series R88D-GT OMNUC G Series R88D-WT Connecting Servo Drives: OMNUC W Series R88D-WT Connecting Servo Drives: OMNUC G Series R88D-WT Connecting Servo Drives: OMNUC W Series R88D-WT Connecting S			Open-collector				Cable lengt	h: 3 m		XW2Z-300J-G15	
Special NO Units  Position Control Unit Cables  SMARTSTEP2 R7D-BP Connecting Servo Drives: OMNUC W Series R88D-WT Connecting Servo Drives: SMARTSTEP R7D-AP Connecting Servo Drives: OMNUC G Series R88D-GT OMNUC G Series R88D-WT Connecting Servo Drives: OMNUC W Series R88D-WT Connecting Servo Drives: OMNUC G Series R88D-WT Connecting Servo Drives: OMNUC G Series R8BD-WT Connecting Servo Drives: OMNUC G Series R88D-WT Cable length: 1 m		Position Control	output		OMNUC G Series R88D-GT		Cable length: 1 m			XW2Z-100J-G5	
Position Control Unit Cables    Connecting Servo Drives: OMNUC W Series R88D-WT   Connecting Servo Drives: SMARTSTEP R7D-AP   Connecting Servo Drives: OMNUC G Series R88D-KT   Connecting Servo Drives: SMARTSTEP2 R7D-BP   Connecting Servo Drives: OMNUC W Series R88D-WT   Connecting Servo Drives: OMNUC G Series R88D-WT   Connecting Servo Drives: OMNUC W Series R88D-WT   Cable length: 1 m							Cable lengt	h: 3 m		XW2Z-300J-G5	
Cable length: 3 m XW2Z-300J-G8  Cable length: 1 m XW2Z-100J-G6  Cable length: 1 m XW2Z-300J-G6  Cable length: 1 m XW2Z-300J-G6  Cable length: 3 m XW2Z-300J-G6  Cable length: 3 m XW2Z-300J-G6  Cable length: 1 m XW2Z-100J-G6  Cable length: 3 m XW2Z-300J-G6  Cable length: 3 m XW2Z-300J-G7  Cable length: 1 m XW2Z-100J-G7  Cable length: 3 m XW2Z-300J-G6  Cable length: 1 m XW2Z-100J-G7  Cable length: 1 m XW2Z-100J-G9  Cable length: 1 m XW2Z-100J-G12  Cable length: 1 m XW2Z-100J-G12  Cable length: 1 m XW2Z-100J-G12  Cable length: 5 m XW2Z-500J-G10  Cable length: 5 m XW2Z-500J-G10  Cable length: 1 m XW2Z-100J-G10  Cable length: 1 m XW2Z-100J-G10  Cable length: 1 m XW2Z-100J-G10  Cable length: 1 m XW2Z-100J-G11						- 2 axes	Cable lengt	h: 1 m		XW2Z-100J-G8	
Connecting Servo Drives: OMNUC G Series R88D-KT Connecting Servo Drives: SMARTSTEP2 R7D-BP Connecting Servo Drives: OMNUC W Series R88D-WT  Connecting Servo Drives: OMNUC W Series R88D-WT  Connecting Servo Drives: Connecting Servo Drives: Connecting Servo Drives: OMNUC W Series R88D-GT OMNUC G Series R88D-GT OMNUC G Series R88D-KT  Connecting Servo Drives: OMNUC G Series R88D-KT  Connecting Servo Drives: OMNUC G Series R88D-KT  Connecting Servo Drives: OMNUC G Series R88D-WT  Connecting Servo Drives: OMNUC G Series R88D-WT  Connecting Servo Drives: OMNUC W Series R88D-WT  Cable length: 1 m		Unit Cables					Cable length: 3 m			XW2Z-300J-G8	
SMARTSTEP2 R7D-BP Connecting Servo Drives: OMNUC W Series R88D-WT Connecting Servo Drives: SMARTSTEP R7D-AP  Connecting Servo Drives: OMNUC G Series R88D-GT OMNUC G Series R88D-GT OMNUC G Series R88D-KT Connecting Servo Drives: SMARTSTEP2 R7D-BP Connecting Servo Drives: OMNUC G Series R88D-GT OMNUC G Series R88D-WT Connecting Servo Drives: SMARTSTEP2 R7D-BP CJ1W-NC234/ NC434  Connecting Servo Drives: OMNUC W Series R88D-WT Cable length: 1 m  XW2Z-100J-G9 Cable length: 1 m  XW2Z-100J-G9 Cable length: 5 m  XW2Z-500J-G9 Cable length: 1 m  XW2Z-100J-G9 Cable length: 1 m  XW2Z-100J-G9 Cable length: 1 m  XW2Z-100J-G9 Cable length: 5 m  XW2Z-500J-G10 Cable length: 1 m  XW2Z-100J-G9 Cable length: 1 m  XW2Z-100J-G7					OMNUC G Series R88D-GT		Cable lengt	h: 1 m		XW2Z-100J-G6	
OMNUC W Series R88D-WT Connecting Servo Drives: SMARTSTEP R7D-AP  Connecting Servo Drives: OMNUC G Series R88D-GT OMNUC G Series R88D-KT  Connecting Servo Drives: OMNUC G Series R88D-KT  Connecting Servo Drives: SMARTSTEP2 R7D-BP  Line-driver output  For CJ1W-NC234/ NC434  Connecting Servo Drives: OMNUC W Series R88D-WT  Cable length: 1 m							Cable lengt	h: 3 m		XW2Z-300J-G6	
SMARTSTEP R7D-AP  Connecting Servo Drives: OMNUC G Series R88D-GT OMNUC G5 Series R88D-KT  Connecting Servo Drives: SMARTSTEP2 R7D-BP  Connecting Servo Drives: SMARTSTEP2 R7D-BP  Connecting Servo Drives: SMARTSTEP2 R7D-BP  Connecting Servo Drives: OMNUC W Series R88D-WT  Cable length: 1 m							Cable lengt	h: 1 m		XW2Z-100J-G7	
Cable length: 5 m XW2Z-500J-G9 Cable length: 1 m XW2Z-10MJ-G9 Cable length: 5 m XW2Z-500J-G9 Cable length: 1 m XW2Z-10MJ-G9 Cable length: 5 m XW2Z-500J-G12 Cable length: 5 m XW2Z-10MJ-G9 Cable length: 1 m XW2Z-10MJ-G12 Cable length: 5 m XW2Z-500J-G12 Cable length: 5 m XW2Z-500J-G12 Cable length: 1 m XW2Z-10MJ-G12 Cable length: 1 m XW2Z-10MJ-G10 Cable length: 5 m XW2Z-500J-G10 Cable length: 1 m XW2Z-10MJ-G10 Cable length: 5 m XW2Z-500J-G10 Cable length: 5 m XW2Z-500J-G10 Cable length: 1 m XW2Z-10MJ-G10 Cable length: 5 m XW2Z-500J-G10 Cable length: 5 m XW2Z-500J-G10 Cable length: 5 m XW2Z-10MJ-G10					0144 DT0TED DED 4D		Cable length: 3 m			XW2Z-300J-G7	
Connecting Servo Drives: SMARTSTEP2 R7D-BP  Line-driver output  For CJ1W-NC234/NC434  NC434  Connecting Servo Drives: OMNUC G5 Series R88D-KT  Connecting Servo Drives: OMNUC W Series R88D-WT  Connecting Servo Drives: OMNUC W Series R88D-WT  Cable length: 10 m							Cable lengt	h: 1 m		XW2Z-100J-G9	
Line-driver output  For CJ1W-NC234/NC434  Connecting Servo Drives: SMARTSTEP2 R7D-BP  Connecting Servo Drives: OMNUC W Series R88D-WT  Connecting Servo Drives: Cable length: 1 m										XW2Z-500J-G9	
Line-driver output  For CJ1W-NC234/ NC434  Connecting Servo Drives: SMARTSTEP2 R7D-BP  Line-driver output  Connecting Servo Drives: OMNUC W Series R88D-WT  Connecting Servo Drives: OMNUC W Series R88D-WT  Connecting Servo Drives: Cable length: 5 m XW2Z-100J-G10  Cable length: 5 m XW2Z-100J-G10  Cable length: 10 m XW2Z-100J-G10  Cable length: 1 m XW2Z-100J-G10  Cable length: 1 m XW2Z-100J-G10  Cable length: 1 m XW2Z-100J-G10  Cable length: 5 m XW2Z-100J-G10					OWINUC GO Series H88D-K1				า		
For CJTW-NC234/ NC434  Connecting Servo Drives: OMNUC W Series R88D-WT  Connecting Servo Drives: Cable length: 5 m					Connecting Servo Drives:						
Line-driver output  CJ1W-NC234/ NC434  Connecting Servo Drives: OMNUC W Series R88D-WT  Connecting Servo Drives: Connecting Servo Drives: Connecting Servo Drives: Cable length: 1 m				For							
Connecting Servo Drives: OMNUC W Series R88D-WT  Cable length: 5 m XW2Z-500J-G10  Cable length: 10 m XW2Z-10MJ-G10  Cable length: 1 m XW2Z-10DJ-G11  Cable length: 5 m XW2Z-10DJ-G11				CJ1W-NC234/		1 axis			n		
OMNUC W Series R88D-WT  Cable length: 10 m			output	NC434	Connecting Servo Drives:						
Cable length: 1 m XW2Z-100J-G11 Connecting Servo Drives: Cable length: 5 m XW2Z-500 LG11											
Connecting Servo Drives:									1		
CALLETOTED DED AD   Cable lettutt. 3 til   AWZZ-300.1-011					Connecting Servo Drives: SMARTSTEP R7D-AP						
SMARTSTEP R7D-AP  Cable length: 10 m									<u> </u>		

Unit classifi-	Product name		Specifications			No. of unit co		rent ump- ı (A)	Model	Standards
Cation			Control output interface No. of axes				5 V	24 V		
				Applicable Servo Drive:		Cable lengtl	n: 1 m		XW2Z-100J-G1	
				OMNUC G Series R88D-GT		Cable lengtl	n: 5 m		XW2Z-500J-G1	
				OMNUC G5 Series R88D-KT		Cable lengtl	n: 10 m	1	XW2Z-10MJ-G1	
				A 1: 11 0 D:	_ 2 axes	Cable lengtl	n: 1 m		XW2Z-100J-G4	
			For CJ1W-NC234/	Applicable Servo Drive: SMARTSTEP2 R7D-BP		Cable lengtl	n: 5 m		XW2Z-500J-G4	
CJ1 Special	Position Control	n Control Line-driver				Cable lengtl	n: 10 m	1	XW2Z-10MJ-G4	
I/O Units	Unit Cables	output	NC434	Analiaahla Cama Dahaa		Cable lengt		n: 1 m		XW2Z-100J-G2
				Applicable Servo Drive: OMNUC W Series R88D-WT	Cable lengt		n: 5 m		XW2Z-500J-G2	
						Cable lengtl	n: 10 m	1	XW2Z-10MJ-G2	
				A 1: 11 0 D:		Cable lengtl	n: 1 m		XW2Z-100J-G3	
				Applicable Servo Drive: SMARTSTEP R7D-AP		Cable length: 5 m		XW2Z-500J-G3		
			SMARTSTEP R7D-AP			Cable lengtl	n: 10 m	ו	XW2Z-10MJ-G3	

#### Position Control Units

Unit classifi-	Product name		Spe	ecifications		No. of unit numbers	cons	rent ump- ı (A)	Model	Standards
cation			Control outp	ut interface	No. of axes	allocated	5 V	24 V		
	Position Control	Pulse train, op	en collector outp	ut	1 axis	1	0.25		CJ1W-NC113	
	Units	Pulse train, op	en collector outp	ut	2 axes	'	0.25		CJ1W-NC213	
		Pulse train, op	en collector outp	ut (See note.)	4 axes	2	0.36		CJ1W-NC413	UC1, CE
		Pulse train, lin	e driver output		1 axis	1	0.25		CJ1W-NC133	001, 02
		Pulse train, lin	e driver output		2 axes	•	0.25		CJ1W-NC233	
		Pulse train, lin	e driver output (S	See note.)	4 axes	2	0.36		CJ1W-NC433	
	Space Unit	Use a CJ1W-S	SP001 Space Un	t if the operating temperature	is 0 to 55	°C.			CJ1W-SP001	UC1, CE
	Comes Bolon	For 1-Axis Pos	or 1-Axis Position Control Unit (without communications support) (CJ				33)		XW2B-20J6-1B	
	Servo Relay Units	For 2- or 4-Axe	s Position Control	Unit (without communications s	support) (0	CJ1W-NC213/	233/41	3/433)	XW2B-40J6-2B	
	· · · · · · · · · · · · · · · · · · ·	For 2- or 4-Axe	or 4-Axes Position Control Unit (with communications sup			1W-NC213/2	33/413	/433)	XW2B-40J6-4A	
				Connecting Servo Drives: OMNUC G5/G/W Series,		Cable lengt	h: 0.5 ı	n	XW2Z-050J-A14	
			For	SMARTSTEP2	1 axis	Cable lengt	gth: 1 m		XW2Z-100J-A14	
			CJ1W-NC113	Connecting Servo Drives: SMARTSTEP Junior/A	i axis	Cable lengt	h: 0.5 ı	n	XW2Z-050J-A16	
		Open-collector		Series		Cable lengt	h: 1 m		XW2Z-100J-A16	
CJ1 Special		output	For CJ1W-NC213/ 413	Connecting Servo Drives: OMNUC G5/G/W Series,		Cable lengt	h: 0.5 ı	n	XW2Z-050J-A15	
I/O Units				SMARTSTEP2	2 axes	Cable lengt	h: 1 m		XW2Z-100J-A15	
				Connecting Servo Drives: SMARTSTEP Junior/A Series		Cable length: 0.5 m		n	XW2Z-050J-A17	
	Position Control					Cable length: 1 m			XW2Z-100J-A17	
	Unit Cables			Connecting Servo Drives: OMNUC G5/G/W Series,	Cable le		h: 0.5 ı	n	XW2Z-050J-A18	
			For	SMARTSTEP2	1 axis	Cable lengt	h: 1 m		XW2Z-100J-A18	
			CJ1W-NC133	Connecting Servo Drives: SMARTSTEP Junior/A		Cable lengt	length: 0.5 m		XW2Z-050J-A20	
		Line-driver		Series		Cable length: 1 m		XW2Z-100J-A20		
		output		Connecting Servo Drives: OMNUC G5/G/W Series,		Cable lengt	h: 0.5 ı	n	XW2Z-050J-A19	
			For CJ1W-NC233/	SMARTSTEP2	2 axes	Cable length: 1 m		XW2Z-100J-A19		
			433	Connecting Servo Drives: SMARTSTEP Junior/A	2 axes	Cable length: 0.5 m		XW2Z-050J-A21		
				Series		Cable lengt	h: 1 m		XW2Z-100J-A21	

Note: The ambient operating temperature for 4-Axes Position Control Units is 0 to 50°C; the allowable voltage fluctuation on the external 24-VDC power supply is 22.8 to 25.2 VDC (24 V ±5%).

#### ■ Position Control Unit with EtherCAT interface

Unit classi-	Product name	Specifications		No. of unit	Current con- sumption (A)		Model	Standards
fication	Product name	Control output interface	No. of axes	allocated	5 V	24 V	Wodel	Standards
			2 axes				CJ1W-NC281 <u>NEW</u>	
	Position Control Unit	t communications.	4 axes	1	0.40		CJ1W-NC481 <u>NEW</u>	
	with EtherCAT interface	Positioning functions: Memory operation, Direct operation by ladder programming	8 axes	0.46		CJ1W-NC881 <u>NEW</u>		
CJ1 CPU Bus Units	88		16 axes				CJ1W-NCF81 <u>NEW</u>	UC1, CE
Dus Omits		Control commands executed by EtherCAT communications.	4 axes				CS1W-NC482 <u>NEW</u>	
		Positioning functions: Memory operation, Direct operation by ladder programming I/O communications: 64 nodes		<b>!</b>	0.46		CS1W-NC882 <u>NEW</u>	

#### Recommended EtherCAT Communications Cables

Category 5 or higher (100BASE-TX) straight cable with double shielding (aluminum tape and braided shielding) is recommended.

#### **Cabel with Connectors**

Wire Gauge and Number of Pairs: AWG22, 2-pair Cable

As of October 2010

Item	Appearance	Recommended manufacturer	Cable length (m)	Model
			0.3	XS5W-T421-AMD-K
Cable with Connectors on Both Ends (RJ45/RJ45)	**		0.5	XS5W-T421-BMD-K
		OMBON	1	XS5W-T421-CMD-K
		OMRON	2	XS5W-T421-DMC-K
Cable with Connectors on Both Ends (M12/RJ45)			5	XS5W-T421-GMC-K
			10	XS5W-T421-JMC-K

Note: The cable length 0.3, 0.5, 1, 2, 3, 5, 10 and 15m are available. For details, refer to Cat.No.G019.

#### **Cabel with Connectors**

Wire Gauge and Number of Pairs: AWG24, 4-pair Cable

As of June 2010

Item	Appearance	Recommended manufacturer	Model
		Tonichi Kyosan Cable, Ltd.	NETSTAR-C5E SAB 0.5 × 4P
Cable		Kuramo Electric Co.	KETH-SB
		SWCC Showa Cable Systems Co.	FAE-5004
Connector		Panduit Corporation	MPS588

#### Wire Gauge and Number of Pairs: AWG22, 2-pair Cable

As of June 2010

Item	Appearance	Recommended manufacturer	Model
Cable		Kuramo Electric Co.	KETH-PSB-OMR *
RJ45 Assembly Connector	nonno	OMRON	XS6G-T421-1 *

 $<sup>\</sup>ensuremath{\boldsymbol{\ast}}$  We recommend you to use above cable and connector together.

## ■ Position Control Units with MECHATROLINK-II interface

Unit classi-	Product name	Repeater		No. of unit		nt con- ion (A)	Model	Standards
fication	Product name	Control output interface	No. of axes	allocated	5 V	24 V	Model	Standards
	Position Control Units with MECHATROLINK-II	Control commands executed by	2 axes				CJ1W-NC271	
	interface	MECHATROLINK-II synchronous communications.	4 axes	1			CJ1W-NC471	UC1. CE
		Direct operation by ladder programming.  Control mode: Position control, speed control, or torque control	16 axes		0.36		CJ1W-NCF71	- 0C1, CE
		7		S			CJ1W-NCF71-MA	
	MECHATROLINK-II Interface Unit	R88D-WT□ OMNUC W-series AC Servo Driv Use the model numbers provided in this cata					FNY-NS115	
		MECHATROLINK-II Cables	Cable ler	ngth: 0.5 m			FNY-W6002-A5	
		(without ring core and USB connector on both ends)	Cable ler	ngth: 1 m			FNY-W6002-01	
		(Yaskawa Electric Corporation)	Cable ler	ngth: 3 m			FNY-W6002-03	<b></b>
CJ1 CPU Bus Units		Note: Can be connected to R88D-GN and R88D-KN only.		ngth: 5 m			FNY-W6002-05	
	MECHATROLINK-II		Cable length: 0.5 m				FNY-W6003-A5	
	Cables	MECHATROLINK-II Cables	Cable length: 1 m				FNY-W6003-01	
		(with ring core and USB connector on both	Cable length: 3 m				FNY-W6003-03	
		ends) (Yaskawa Electric Corporation)	Cable ler	ngth: 5 m			FNY-W6003-05	
		Use the model numbers provided in this	Cable ler	ngth: 10 m			FNY-W6003-10	
		catalog when ordering from OMRON.	Cable ler	ngth: 20 m			FNY-W6003-20	
			Cable ler	ngth: 30 m			FNY-W6003-30	
	MECHATROLINK-II Terminating Resistors	Terminating Resistor for MECHATROLINK-II Use the model numbers provided in this cata				I.	FNY-W6022	
	MECHATROLINK-II Repeater	Repeater					FNY-REP2000	

#### ■ Motion Control Units with MECHATROLINK-II interface

Unit classi-	Product name	Specifications	No. of unit numbers		nt con- ion (A)	Model	Standards	
lication			allocated	5 V	24 V			
	Motion Control Units with MECHATROLINK-II interface	Position, speed, and torque commands by MECHATROLINK-II 32 axes max. (Physical axes: 30, Virtual axes: 2) Motion control language	1	0.6		CJ1W-MCH71	UC1, CE	
	MECHATROLINK-II Interface Unit	R88D-WT□ OMNUC W-series AC Servo Driver (Yaskawa Use the model numbers provided in this catalog when ord		FNY-NS115				
		MECHATROLINK-II Cables	Cable length	: 0.5 m		FNY-W6002-A5		
	MECHATROLINK-II Cables	(without ring core and USB connector on both ends)	Cable length: 1 m			FNY-W6002-01		
		(Yaskawa Electric Corporation)  Note: Can be connected to R88D-GN and R88D-KN only.	Cable length	: 3 m		FNY-W6002-03	]	
		Note: Can be connected to R88D-GN and R88D-KN only.	Cable length: 5 m  Cable length: 0.5 m			FNY-W6002-05		
			Cable length	: 0.5 m		FNY-W6003-A5		
CJ1 CPU Bus Units		MECHATROLINK-II Cables	Cable length	: 1 m		FNY-W6003-01		
bus units		(with ring core and USB connector on both ends)	Cable length: 3 m			FNY-W6003-03		
		(Yaskawa Electric Corporation)	Cable length: 5 m			FNY-W6003-05		
		Use the model numbers provided in this catalog when ordering from OMRON.	Cable length: 10 m			FNY-W6003-10		
		3 · · · · · · · · · · · · · · · · · · ·	Cable length: 20 m			FNY-W6003-20		
			Cable length			FNY-W6003-30		
	MECHATROLINK-II Terminating Resistors	Terminating Resistor for MECHATROLINK-II (Yaskawa Ele Use the model numbers provided in this catalog when ord				FNY-W6022		
	MECHATROLINK- II Repeater	For more than 15 slaves/30 m				FNY-REP2000		
	MECHATROLINK-II 24-VDC I/O Module	Inputs: 64 Outputs: 64				FNY-IO2310		
	MECHATROLINK-II Counter Module	Reversible counter, 2 words				FNY-PL2900		
	MECHATROLINK-II Pulse Output Module	Pulse train positioning, 2 words			FNY-PL2910			

Note: The CJ1W-MCH71 requires the space of three Units (but just one unit number). A maximum of 10 Units can be mounted on a single CJ-series Rack, up to three CJ1W-MCH71 Motion Control Units plus one other Unit can be mounted per Rack.

#### **■** Serial Communications Units

Unit clas-	Product name	Sp	pecifications	No. of unit	Current c		Model	Standards
sification	r roudet name	Communications Interface	Communications functions	allocated	5 V	24 V	Model	Standards
	Serial Com- munications Units High-speed type	2 RS-232C ports	The following functions can be		0.28 (See note 1.)		CJ1W-SCU22	
CJ1		2 RS-422A/485 ports	selected for each port: Protocol macro Host Link NT Links (1:N mode) Serial Gateway No-protocol Modbus-RTU Slave	1	0.40		CJ1W-SCU32	UC1, N, L, CE
CPU Bus Units		1 RS-232C port and 1 RS-422A/485 port			0.36 (See note 1.)		CJ1W-SCU42	
	Serial Com- munications Units	2 RS-232C ports	The following functions can be selected for each port:  Protocol macro		0.28 (See note 1.)		CJ1W-SCU21-V1	
U		2 RS-422A/485 ports	Host Link NT Links (1:N mode)	1	0.38		CJ1W-SCU31-V1	UC1, N, L, CE
		1 RS-232C port and 1 RS-422A/485 port	Serial Gateway (See note 2.) No-protocol (See note 3.) Modbus-RTU Slave (See note 4.)		0.38 (See note 1.)		CJ1W-SCU41-V1	

Note 1. When an NT-AL001 RS-232C/RS-422A Conversion Unit is used, this value increases by 0.15 A/Unit.

- The Serial Gateway function is enabled only for Serial Communications Units of unit version 1.2 and later.
   The no-protocol function is enabled only for Serial Communications Units of unit version 1.2 and later (and a CPU Unit of unit version 3.0 or later is also required).
- 4. The Modbus-RTU Slave function is enabled only for Serial Communications Units of unit version 1.3 and later.

#### **■** EtherNet/IP Unit

			Specifications			Current con- sumption (A)			
Unit clas- sification		Communica- tions cable	Communications functions	Max.Units mountable per CPU Unit	No. of unit numbers allocated	5 V	24 V	Model	Standards
CJ1 CPU Bus Unit	EtherNet/IP Unit	STP (shielded twisted-pair) cable of category 5, 5e, or higher.	Tag data link message service	8	1	0.41	-1	CJ1W-EIP21	UC1, N, L, CE

#### **■** Ethernet Unit

			Specifications			Current con- sumption (A)			
Unit clas- sification		Communica- tions cable	Communications functions	Max.Units mountable per CPU Unit	No. of unit numbers allocated	5 V	24 V	Model	Standards
CJ1 CPU Bus Unit	Ethernet Unit	100Base-TX	FINS communications service (TCP/IP, UDP/IP), FTP server functions, socket services, mail transmission service, mail reception (remote command receive), automatic adjustment of PLC's built-in clock, server/host name specifications	4 (See note.)	1	0.37		CJ1W-ETN21	UC1, N, L, CE

Note: Up to three Ethernet Units can be connected to a CJ1M-CPU1□-ETN CPU Unit.

#### Industrial Switching Hubs

		Specifications				Current		
Product name	Appearance	Functions	No. of ports	Failure detection	Accessories	consumption (A)	Model	Standards
		Quality of Service (QoS):	3	No	Power supply connector	0.22	W4S1-03B	UC, CE
Industrial Switching		EtherNet/IP control data priority Failure detection:	5	No		0.22	W4S1-05B	
Hubs		Broadcast storm and LSI error detection 10/100BASE-TX, Auto-Negotiation	5	Yes	Power supply connector     Connector for informing error	0.22	W4S1-05C	CE

#### **■** Controller Link Units

#### ● Controller Link Units

Unit clas- sification name		Specification	s		No. of unit					
		Communications cable	Communica- tions type	Duplex support	Max. Units mountable per CPU Unit	numbers allocated	5 V	24 V	Model Star	Standards
CJ1 CPU Bus Unit	Controller Link Unit	Wired shielded twisted-pair cable (See note.)	Data links and message service	No	8	1	0.35		CJ1W-CLK23	UC1, N, L,

Note: Use the following special cable for shielded, twisted-pair cable.

◆ ESVC0.5 × 2C-13262 (Bando Electric Wire: Japanese Company)

- $\bullet$  ESNC0.5  $\times$  2C-99-087B (Nihon Electric Wire & Cable Corporation: Japanese Company)
- ullet ESPC 1P  $\times$  0.5 mm² (Nagaoka Electric Wire Co., Ltd.: Japanese Company)
- Li2Y-FCY2 × 0.56qmm (Kromberg & Schubert, Komtec Department: German Company)
- 1 × 2 × AWG-20PE+Tr.CUSN+PVC (Draka Cables Industrial: Spanish Company)
- #9207 (Belden: US Company)

#### Controller Link Support Boards

Unit	Specification					
classification	Communications cable type		Accessories	Model	Standards	
Controller Link Support Board for PCI Bus	Wired shielded twisted-pair cable	Data link and message service	CD-ROM × 1 (See note.) INSTALLATION GUIDE (W467) × 1 Communications connector × 1	3G8F7-CLK23-E	CE	

Note: The CD-ROM contains the following software.

- Controller Link (PCI) Driver
- FinsGateway Version 2003 (PCI-CLK Edition)
- FinsGateway Version 3 (PCI-CLK Edition)
- Setup Diagnostic Utility
- C Library

#### Repeater Units

Unit classification	Specifications	Model	Standards
Controller Link Repeater Unit	Wire-to-wire Model	CS1W-RPT01	
	Wire-to-Optical (H-PCF) Model (See note 2.)	CS1W-RPT02	UC1, CE
	Wire-to-Optical (GI) Model (See note 3.)	CS1W-RPT03	

- Note 1. Using Repeater Units enables T-branches and long-distance wiring for Wired Controller Link networks. 62-node configurations, and converting part of the network to optical cable.
  - 2. When using wire-to-optical (H-PCF) cable, use a H-PCF cable (for both Controller Link and SYSMAC LINK) or a H-PCF optical fiber cable with connector.
  - 3. When using wire-to-optical (GI) cable, use a GI optical cable (for Controller Link).

#### Relay Terminal Block

Unit classification	Specifications	Model	Standards
Relay Terminal Block for Wired Controller Link Unit	Has for Wired Controller Link Heits (act of 5)	CHW TRIOI	
	Use for Wired Controller Link Units (set of 5).	CJ1W-TB101	

Note: Controller Link Units can be replaced without stopping the communications of the entire network if a Relay Terminal Block is installed in advance on the Unit in a Wired Controller Link network. Relay Blocks cannot be used on Controller Link Support Boards.

#### H-PCF Cables and Optical Connectors

Name	Ар	plication/construction	Spe	ecifications		Model	Standards
				Black	10 m	S3200-HCCB101	
		(1)		Black	50 m	S3200-HCCB501	
		(3)		Black	100 m	S3200-HCCB102	
Optical Fiber Cables	Controller	(5)		Black	500 m	S3200-HCCB502	
	Link, SYSMAC LINK, SYSBUS	(1) Optical fiber single-core cord (2) Tension member (plastic-	·   Diack	1,000 m	S3200-HCCB103	1	
		sheathed wire)	tension member	Orange	10 m	m S3200-HCCO101	
		(3) Filler (plastic)		Orange	9 100m S3200-l	S3200-HCCO501	
		(4) Filler surrounding signal wires (plastic, yarn, or fiber)		Orange		S3200-HCCO102	
		(5) Holding tape (plastic)		Orange		S3200-HCCO502	
		(6) Heat-resistant PV sheath		Orange	1,000 m	m S3200-HCCO502	
Optical Connec-	onnec- longer CS1W-RPT02 cs1W-RPT02		Half lock			S3200-COCF2571	
tors (Crimp- cut)			Full lock			S3200-COCF2071	

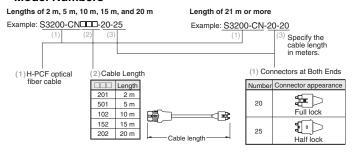
#### H-PCF Optical Fiber Cables with Connectors (Black Composite Cables with Two-Optical Lines and Two Power Supply Lines)

Application	Appearance	Model	Stan- dards
	<b>5</b>	S3200-CN□□□-20-20	
Controller Link, SYSMAC Link		S3200-CN□□-20-25	
		S3200-CN□□□-25-25	

#### Cable Length

The following cable lengths are available: 2 m, 5 m, 15 m, 20 m. For lengths of 21 m or more, contact your OMRON sales representative.

#### Model Numbers



#### Optical Connector Assembly Tool

Product Name	Applicable Unit	Model	Manufacturer	Stan- dards
Optical Fiber Assem- bly Tool (See note.)	This tool is used on site for mounting crimp-cut connectors and hard plastic-clad silica optical fiber for optical transmission systems of SYSMAC C-series SYSBUS, SYSMAC LINK, and Controller Link.	CAK-0057	Sumitomo Electric Industries, Ltd.	

Note: There is a risk of quality problems when using cables assembled by typical users, so we recommend purchasing cables with preattached connectors or having a qualified technician assemble the cables.
Optical connectors for H-PCF Optical Cables with Connectors are adhesive polished.

#### Gl Optical Cables

A qualified technician must select, assemble, and install GI Optical Fiber Cable, so always let an optical cable specialist handle the GI cable.

Usable Optical Cables and Optical Connectors

- Optical fiber types: Graded, indexed, multi-mode, all quartz glass, fiber (GI-type AGF cable)
- Optical fiber construction (core diameter/clad diameter):
   62.5/125 μm or 50/125 μm
- Optical fiber optical characteristics of optical fiber: Refer to the tables.
- Optical connector: ST connector (IEC-874-10)

#### • 50/125 μm AGF Cable

Item	Minimum	Standard	Maximum	Rem	arks	
Numerical Aperture (N.A)		0.21				
			3.0 Lf	0.5 km ≤ Lf		
Transmis- sion loss (dB)		3.0 Lf + 0.2	$ \begin{array}{c c} 0.2 \text{ km} \leq \\ \text{Lf} \leq 0.5 \\ \text{km} \end{array} \hspace{0.5cm} \lambda = 0.8 \; \mu \\ \text{Ta} = 25^{\circ} 0.5 \; \mu $			
			3.0 Lf + 0.4	Lf ≤ 0.2 km		
Connection loss (dB)			1.0	$\lambda = 0.8 \ \mu m,$ one location		
Transmis- sion band- width (MHz-km)	500			$\lambda$ = 0.85 $\mu$ m (LD)		

Lf is fiber length in km, Ta is ambient temperature, and  $\lambda$ : is the peak wavelength of the test light source.

#### • 62.5/125 μm AGF Cable

Item	Minimum	Standard	Maximum	Rem	arks	
Numerical Aperture (N.A)		0.28				
		3.5 Lf 0.5 km ≤ Lf				
Transmis- sion loss (dB)			3.5 Lf + 0.2	0.2 km ≤ Lf ≤ 0.5 km	$\lambda$ = 0.8 $\mu$ m Ta = 25°C	
			3.5 Lf + 0.4	Lf ≤ 0.2 km		
Connection loss (dB)			1.0	$\lambda = 0.8 \ \mu m,$ one location		
Transmis- sion band- width (MHz-km)	200			$\lambda$ = 0.85 $\mu$ m (LD)		

Lf is fiber length in km, Ta is ambient temperature, and  $\lambda$  is the peak wavelength of the test light source.

#### **■** FL-net Unit

Unit classifi- cation Product n					No. of unit	Current con- sumption (A)			
	Product name	Communica- tions interface	Communications functions	Max. Units mountable per CPU Units	numbers allocated	5 V	24 V	Model	Standards
CJ1 CPU Bus Units	FL-net Unit	100Base-TX	With FL-net Ver. 2.0 specifications (OPCN-2) Data links and message service	4	1	0.37		CJ1W-FLN22	UC1, CE

## ■ DeviceNet Unit

Unit classifi- cation	Product name	Specifications	Communications type	No. of unit numbers		nt con- ion (A)	Model	Standards
				allocated	5 V	24 V		
CJ1 CPU Bus Units	DeviceNet Unit	Functions as master and/or slave; allows control of 32,000 points max. per master.	Remote I/O communications master (fixed or user-set allocations)     Remote I/O communications slave (fixed or user-set allocations)     Message communications	1	0.29		CJ1W-DRM21	UC1, N, L, CE

## **■** CompoNet Master Unit

Unit classifi- cation	Product name		No. of unit	Current con- sumption (A)		Model	Standards	
		Communications functions	No. of I/O points per Master Unit	allocated	5 V	24 V	Miodel	Standards
CJ1 Special I/O Units	CompoNet Master Unit	Remote I/O communications     Message communications	Word Slaves: 2,048 max. (1.024 inputs and 1,024 outputs) Bit Slaves: 512 max. (256 inputs and 256 outputs)	1, 2, 4, or 8	0.4		CJ1W-CRM21	U, U1, N, L, CE,

## ■ CompoBus/S Master Unit

Unit classifi- cation	Product name	Specifications			No. of unit	Current con- sumption (A)			
		Communications functions	No. of I/O points	Max. Units mountable per CPU Unit	numbers allocated	5 V	24 V	Model	Standards
CJ1 Special I/O Units	CompoBus/S Master Unit	Remote I/O communications	256 max. (128 inputs and 128 outputs)	40	1 or 2 (variable)	0.15		CJ1W-SRM21	UC1, N, L, CE,
			128 max. (64 inputs and 64 outputs)						

#### **■ ID Sensor Units**

Unit classification	Product name	Specifications			No. of unit	Current consumption (A)			
		Connected ID Systems	No. of con- nected R/W heads	External power supply	numbers allocated	5 V	24 V	Model	Standards
	ID Sensor Units	V680 Series RFID System	1	Not required.	1	0.26	0.13 (See note.)	CJ1W-V680C11	UC, CE
			2		2	0.32	0.26	CJ1W-V680C12	
		V600 Series RFID System	1	Not required.	1	0.26	0.12	CJ1W-V600C11	UC, CE
			2		2	0.32	0.24	CJ1W-V600C12	

Note: To use a V680-H01 Antenna, refer to the V680 Series RFID System Catalog (Cat. No. Q151).

## ■SYSMAC SPU (High-speed Data Storage Unit)

Unit classification	Product name	Specifi	No. of unit numbers allocated	Current consumption (A)		Model	Standards	
		PC Card slot	Ethernet (LAN) port	anocateu	5 V	24 V		
	SYSMAC SPU (High-speed Data Storage Unit)	CF Card Type I/II × 1 slot Use an OMRON HMC- EF□□□ Memory Card.	1 port (10/100Base-TX)	1	0.56		CJ1W-SPU01-V2	UC1, CE
CJ1 CPU Bus Units	SPU- Console (See note.)		pling settings, etc., for High-sp ng settings for this Unit)	eed Data Collection Units WS02-SPTC1-V2				
	SYSMAC SPU Data Manage-		by SYSMAC SPU Data Managematically acquired at the personal control of the per	red at the personal			WS02-EDMC1-V2	
	ment Mid- dleware	computer, and can OS: Windows 2000, XP, Vista		5 licenses		WS02-EDMC1-V2L05		
	Memory Cards	Flash memory, 128 MB		Note:  Memory Card is required for		HMC-EF183		
	Cards	Flash memory, 256 MB				HMC-EF283		
		Flash memory, 512 MB		data collecti	on.	HMC-EF583		

Note: SPU-Console versions lower than version 2.0 cannot connect to SYSMAC SPU Units with unit versions of 2.0 or later.

#### Read and Understand this Catalog

Please read and understand this catalog before purchasing the products. Please consult your OMRON representative if you have any questions or comments.

#### Warranty and Limitations of Liability

#### WARRANTY

OMRON's exclusive warranty is that the products are free from defects in materials and workmanship for a period of one year (or other period if specified) from date of sale by OMRON.

OMRON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, REGARDING NON-INFRINGEMENT, MERCHANTABILITY, OR FITNESS FOR PARTICULAR PURPOSE OF THE PRODUCTS. ANY BUYER OR USER ACKNOWLEDGES THAT THE BUYER OR USER ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE. OMRON DISCLAIMS ALL OTHER WARRANTIES, EXPRESS OR IMPLIED.

#### LIMITATIONS OF LIABILITY

OMRON SHALL NOT BE RESPONSIBLE FOR SPECIAL, INDIRECT, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS, OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED ON CONTRACT, WARRANTY, NEGLIGENCE, OR STRICT LIABILITY.

In no event shall the responsibility of OMRON for any act exceed the individual price of the product on which liability is asserted.

IN NO EVENT SHALL OMRON BE RESPONSIBLE FOR WARRANTY, REPAIR, OR OTHER CLAIMS REGARDING THE PRODUCTS UNLESS OMRON'S ANALYSIS CONFIRMS THAT THE PRODUCTS WERE PROPERLY HANDLED, STORED, INSTALLED, AND MAINTAINED AND NOT SUBJECT TO CONTAMINATION, ABUSE, MISUSE, OR INAPPROPRIATE MODIFICATION OR REPAIR.

#### **Application Considerations**

#### SUITABILITY FOR USE

OMRON shall not be responsible for conformity with any standards, codes, or regulations that apply to the combination of products in the customer's application or use of the products.

Take all necessary steps to determine the suitability of the product for the systems, machines, and equipment with which it will be used.

Know and observe all prohibitions of use applicable to the products.

NEVER USE THE PRODUCTS FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCTS ARE PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

#### PROGRAMMABLE PRODUCTS

OMRON shall not be responsible for the user's programming of a programmable product, or any consequence thereof.

#### Disclaimers

#### **CHANGE IN SPECIFICATIONS**

Product specifications and accessor ies may be changed at any time based on improvements and other reasons. Consult with your OMRON representative at any time to confirm actual specifications of purchased products.

#### **DIMENSIONS AND WEIGHTS**

Dimensions and weights are nominal and are not to be used for manufacturing purposes, even when tolerances are shown.

#### PERFORMANCE DATA

Performance data given in this catalog is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of OMRON's test conditions, and the users must correlate it to actual application requirements. Actual performance is subject to the OMRON Warranty and Limitations of Liability.



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